

COURSE CONTENT AND OUTCOMES OF ELECTRICAL AND ELECTRONICS ENGINEERING (Effective from Academic year 2018-19)

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) and Outcome Based Education (OBE) SEMESTER - III

TRANSFORM CALCULUS, FOURIER SERIES AND NUMERICAL TECHNIQUES (Common to all Programmes)

| (Common to an Programmes) | | | | |
|------------------------------|---------|------------|----|--|
| Course Code | 18MAT31 | CIE Marks | 40 | |
| Teaching Hours/Week (L: T:P) | (2:2:0) | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |

Course Learning Objectives:

- To have an insight into Fourier series, Fourier transforms, Laplace transforms, Difference equations and Z-transforms.
- To develop the proficiency in variational calculus and solving ODE's arising in engineering applications, using numerical methods.

Module-1

Laplace Transform: Definition and Laplace transforms of elementary functions (statements only). Laplace transforms of Periodic functions (statement only) and unit-step function – problems.

Inverse Laplace Transform: Definition and problems, Convolution theorem to find the inverse Laplace transforms (without Proof) and problems. Solution of linear differential equations using Laplace transforms. **Module-2**

Fourier Series: Periodic functions, Dirichlet's condition. Fourier series of periodic functions period 2π and arbitrary period. Half range Fourier series. Practical harmonic analysis.

Module-3

Fourier Transforms: Infinite Fourier transforms, Fourier sine and cosine transforms. Inverse Fourier transforms. Problems.

Difference Equations and Z-Transforms: Difference equations, basic definition, z-transform-definition, Standard z-transforms, Damping and shifting rules, initial value and final value theorems (without proof) and problems, Inverse z-transform and applications to solve difference equations.

Module-4

Numerical Solutions of Ordinary Differential Equations(ODE's):

Numerical solution of ODE's of first order and first degree- Taylor's series method, Modified Euler's method. Runge -Kutta method of fourth order, Milne's and Adam-Bash forth predictor and corrector method (No derivations of formulae)-Problems.

Module-5

Numerical Solution of Second Order ODE's: Runge-Kutta method and Milne's predictor and corrector method. (No derivations of formulae).

Calculus of Variations: Variation of function and functional, variational problems, Euler's equation, Geodesics, hanging chain, problems.

- CO1: Use Laplace transform and inverse Laplace transform in solving differential/ integral equation arising in network analysis, control systems and other fields of engineering.
- CO2: Demonstrate Fourier series to study the behaviour of periodic functions and their applications in system communications, digital signal processing and field theory.
- CO3: Make use of Fourier transform and Z-transform to illustrate discrete/continuous function arising in wave and heat propagation, signals and systems.
- CO4: Solve first and second order ordinary differential equations arising in engineering problems using single step and multistep numerical methods.
- CO5:Determine the externals of functionals using calculus of variations and solve problems arising in dynamics of rigid bodies and vibrational analysis.

ELECTRIC CIRCUIT ANALYSIS Course Code 18EE32 CIE Marks 40 Teaching Hours/Week (L: T:P) SEE Marks (3:2:0)60 Exam Hours Credits 04 03 **Course Learning Objectives:** • To familiarize the basic laws, source transformations, theorems and the methods of analyzing electrical circuits. To explain the use of network theorems and the concept of resonance. To familiarize the analysis of three-phase circuits, two port networks and networks with non-sinusoidal inputs. To explain the importance of initial conditions, their evaluation and transient analysis of R-L and R-C circuits. To impart basic knowledge on network analysis using Laplace transforms. Module-1 Basic Concepts: Active and passive elements, Concept of ideal and practical sources. Source transformation and Source shifting, Concept of Super-Mesh and Super node analysis. Analysis of networks by (i) Network reduction method including star – delta transformation, (ii) Mesh and Node voltage methods for ac and DC circuits with independent and dependent sources. Duality. Module-2 Network Theorems: Super Position theorem, Reciprocity theorem, Thevenin's theorem, Norton's theorem, Maximum power transfer theorem and Millman's theorem. Analysis of networks, with and without dependent ac and DC sources. Module-3 Resonant Circuits: Analysis of simple series RLC and parallel RLC circuits under resonances. Problems on Resonant frequency, Bandwidth and Quality factor at resonance Transient Analysis: Transient analysis of RL and RC circuits under DC excitations: Behavior of circuit elements under switching action $(t = 0 \text{ and } t = \infty)$, Evaluation of initial conditions. Module-4 Laplace Transformation: Laplace transformation (LT), LT of Impulse, Step, Ramp, Sinusoidal signals and shifted functions. Waveform synthesis. Initial and Final value theorems. Module-5 Unbalanced Three Phase Systems: Analysis of three phase systems, calculation of real and reactive Powers by direct application of mesh and nodal analysis. Two Port networks: Definition, Open circuit impedance, Short circuit admittance and Transmission parameters and their evaluation for simple circuits, relationships between parameter sets. . **Course Outcomes:** At the end of the course the student will be able to: • Understand the basic concepts, basic laws and methods of analysis of DC and AC networks and reduce the complexity of network using source shifting, source transformation and network reduction using transformations. • Solve complex electric circuits using network theorems. • Discuss resonance in series and parallel circuits and also the importance of initial conditions and their evaluation. • Synthesize typical waveforms using Laplace transformation. • Solve unbalanced three phase systems and also evaluate the performance of two port networks

TRANSFORMERS AND GENERATORS

| 11 | AND ORNERS AND | ULIVERATORS | |
|------------------------------|----------------|-------------|----|
| Subject Code | 18EE33 | CIE Marks | 40 |
| Number of Lecture Hours/Week | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course Learning Objectives:

- To understand the concepts of transformers and their analysis.
- To suggest a suitable three phase transformer connection for a particular operation.
- To understand the concepts of generator and to evaluate their performance.
- To explain the requirement for the parallel operation of transformers and synchronous generators.

Module-1

Single phase Transformers: Operation of practical transformer under no-load and on-load with phasor diagrams. Open circuit and Short circuit tests, calculation of equivalent circuit parameters and predetermination of efficiency-commercial and all-day efficiency. Voltage regulation and its significance.

Three-phase Transformers: Introduction, Constructional features of three-phase transformers. Choice between single unit three-phase transformer and a bank of three single-phase transformers. Transformer connection for three phase operation– star/star, delta/delta, star/delta, zigzag/star and V/V, comparative features. Phase conversion-Scott connection for three-phase to two-phase conversion. Labeling of three-phase transformer terminals, vector groups.

Module-2

Tests, Parallel Operation of Transformer & Auto Transformer: Polarity test, Sumpner's test, separation of hysteresis and eddy current losses

Parallel Operation of Transformers: Necessity of Parallel operation, conditions for parallel operation– Single phase and three phase. Load sharing in case of similar and dissimilar transformers. **Auto transformers and Tap changing transformers:** Introduction to autotransformer-copper economy, equivalent circuit, no load and on load tap changing transformers.

Module-3

Three-Winding Transformers & Cooling of Transformers: Three-winding transformers. Cooling of transformers.

Direct current Generator: Armature reaction, Commutation and associated problems,

Synchronous Generators: Armature windings, winding factors, e.m.f equation. Harmonics–causes, reduction and elimination. Armature reaction, Synchronous reactance, Equivalent circuit.

Module-4

Synchronous Generators Analysis: Alternator on load. Excitation control for constant terminal voltage. Voltage regulation. Open circuit and short circuit characteristics, Assessment **U**f reactance-short circuit ratio, synchronous reactance, Voltage regulation by EMF, MMF and ZPF

Module-5

Synchronous Generators (Salient Pole): Effects of saliency, two-reaction theory, Parallel operation of generators and load sharing. Methods of Synchronization, Synchronizing power, Determination of $X_d \& X_q$ – slip test

Performance of Synchronous Generators: Power angle characteristic (salient and non salient pole), power angle diagram, reluctance power, Capability curve for large turbo generators. Hunting and damper windings.

- •Understand the construction and operation of 1-phase, 3-Phase transformers and Autotransformer.
- •Analyze the performance of transformers by polarity test, Sumpner's Test, phase conversion, 3-phase connection, and parallel operation.
- •Understand the construction and working of AC and DC Generators.
- •Analyze the performance of the AC Generators on infinite bus and parallel operation.
- •Determine the regulation of AC Generator by Slip test, EMF, MMF, and ZPF Methods.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - III

| ANALOG ELECTRONIC CIRCUITS | | | | |
|------------------------------|--------|------------|----|--|
| Subject Code | 18EE34 | CIE Marks | 40 | |
| Number of Lecture Hours/Week | 2:2:0 | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |

Course Learning Objectives:

• Provide the knowledge for the analysis of diode and transistor circuits.

• Develop skills to design the electronic circuits like amplifiers and oscillators.

Module-1

Diode Circuits: Diode clipping and clamping circuits.

Transistor Biasing and Stabilization: Operating point, analysis and design of fixed bias circuit, self- bias circuit, Emitter stabilized bias circuit, voltage divider bias circuit, stability factor of different biasing circuits. Problems. Transistor switchingcircuits.

Module-2

Transistor at Low Frequencies: BJT transistor modelling, CE fixed bias configuration, voltage divider bias, emitter follower, CB configuration, collector feedback configuration, analysis using h – parameter model, relation between h – parameters model of CE, CC and CB modes, Millers theorem and its dual.

Module-3

Multistage Amplifiers: Cascade and cascade connections, Darlington circuits, analysis and design. Feedback Amplifiers: Feedback concept, different types, practical feedback circuits, analysis and design of feedback circuits.

Module-4

Power Amplifiers: Amplifier types, analysis and design of different power amplifiers, **Oscillators**: Principle of operation, analysis and derivation of frequency of oscillation of phase shift oscillator, Wien bridge oscillator, RF and crystal oscillator and frequency stability.

Module-5

FETs: Construction, working and characteristics of JFET and MOSFET. Biasing of JFET and MOSFET. Analysis and design of JFET (only common source configuration with fixed bias) and MOSFET amplifiers

- Obtain the output characteristics of clipper and clamper circuits.
- Design and compare biasing circuits for transistor amplifiers & explain the transistor switching.
- Explain the concept of feedback, its types and design of feedback circuits
- Design and analyze the power amplifier circuits and oscillators for different frequencies.
- Design and analysis of FET and MOSFET amplifiers.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - III

| DIGITAL SYSTEM DESIGN | | | | |
|------------------------------|--------|------------|----|--|
| Subject Code | 18EE35 | CIE Marks | 40 | |
| Number of Lecture Hours/Week | 3:0:0 | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |

Course Learning Objectives:

- Illustrate simplification of Algebraic equations using Karnaugh Maps and Quine- McClusky Techniques.
- Design combinational logic circuits.
- Design Decoders, Encoders, Digital Multiplexer, Adders, Subtractors and Binary Comparators
- Describe Latches and Flip-flops, Registers and Counters.
- Analyze Mealy and Moore Models.
- Develop state diagrams, Synchronous Sequential Circuits and to understand the basics of various Memories.

Module-1

Principles of Combinational Logic: Definition of combinational logic, canonical forms, Generation of switching equations from truth tables, Karnaugh maps-3,4,5 variables, Incompletely specified functions (Don't care terms) Simplifying Max term equations, Quine-McCluskey minimization technique, Quine-McCluskey using don't care terms, Reduced prime implicants Tables.

Module-2

Analysis and Design of Combinational logic: General approach to combinational logic design, Decoders, BCD decoders, Encoders, digital multiplexers, Using multiplexers as Boolean function generators, Adders and subtractors, Cascading full adders, Look ahead carry, Binary comparators.

Module-3

Flip-Flops: Basic Bistable elements, Latches, Timing considerations, The master-slave flip-flops (pulse-triggered flip-flops): SR flip-flops, JK flip-flops, Edge triggered flip- flops, Characteristic equations.

Module - 4

Flip-Flops Applications: Registers, binary ripple counters, synchronous binary counters, Counters based on shift registers, Design of a synchronous counter, Design of a synchronous mod-n counter using clocked T, JK, D and SR flip-flops.

Module – 5

Sequential Circuit Design: Mealy and Moore models, State machine notation, Synchronous Sequential circuit analysis, Construction of state diagrams, counter design.

Memories: Read only and Read/Write Memories, Programmable ROM, EPROM, Flash memory.

Course Outcomes: After studying this course, students will be able to:

- Develop simplified switching equation using Karnaugh Maps and QuineMcClusky techniques.
- Design Multiplexer, Encoder, Decoder, Adder, Subtractors and Comparator as digital combinational control circuits.
- Design flip flops, counters, shift registers as sequential control circuits.
- Develop Mealy/Moore Models and state diagrams for the given clocked sequential circuits.
- Explain the functioning of Read only and Read/Write Memories, Programmable ROM, EPROM and Flash memory.

| | | | ication (OBE) |
|--|--|---|---|
| | | STER - III | |
| | | IC MEASUREMENTS (C | |
| Subject Code | 18EE36 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P | | SEE Marks | 60 |
| Credits Course Learning Objectives: | 03 | Exam Hours | 03 |
| To measure resistance, inductar resistance. To study the construction and wo To study the adjustments, calibr instruments. | orking of various | meters used for measureme | ent. |
| Module-1 | | | |
| Measurement of Resistance: Wheatsto Earth resistance measurement by fall of Measurement of Inductance and Ca bridge, Hay's bridge, Anderson's bridg | f potential metho apacitance: Sour | d and by using Megger. rces and detectors, Maxwo | ell's inductance and capacita |
| Module-2 | | | |
| Module-3 Extension of Instrument Ranges: Demultipliers. Construction and theory of CT and PT. Turns compensation, Illustre Magnetic measurements: Introduction | f instrument tran ative examples, s | sformers, Desirable charac Silsbee's method of testing | cterises, Errors of CT. |
| | | | |
| Module-4 | | | |
| Electronic and Digital Instruments: I of electronic instruments. True rms reatype DVM, Integrating type DVM and electronic energy meter (with block significance in billing. | ading voltmeter. nd Successive - | Electronic multimeters. D approximation DVM. Q | igital voltmeters (DVM) - Rameter. Principle of working |
| odule-5 | | | |
| | rmats, segment d | lisplays Dot matrix displa | D 1 |
| play Devices: Introduction, character fo lays. Cathode ray tubes, Light emitting id vapour and Visual displays. ording Devices: Introduction, Strip entiometer type recorders, Bridge type re dxy recorders. Digital tape recording, Ul | g diodes, Liquid chart recorders, ecorders, LVDT | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch | candescent, Fluorescent, s, Null balance recorders, aart |
| lays. Cathode ray tubes, Light emitting iid vapour and Visual displays. ording Devices: Introduction, Strip entiometer type recorders, Bridge type re lxy recorders. Digital tape recording, Ul | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E | candescent, Fluorescent, s, Null balance recorders, aart |
| lays. Cathode ray tubes, Light emitting iid vapour and Visual displays. ording Devices: Introduction, Strip entiometer type recorders, Bridge type re axy recorders. Digital tape recording, Ul urse Outcomes: At the end of the course | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder e the student will | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E be able to: | candescent, Fluorescent, s, Null balance recorders, nart CG) ■ |
| lays. Cathode ray tubes, Light emitting tid vapour and Visual displays. ording Devices: Introduction, Strip entiometer type recorders, Bridge type recorders, Bridge type recorders. Digital tape recording, Ul urse Outcomes: At the end of the course Measure resistance, inductance and other strands. | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder e the student will capacitance using | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E be able to: g bridges and determine ear | candescent, Fluorescent, s, Null balance recorders, nart CG) ■ |
| lays. Cathode ray tubes, Light emitting tid vapour and Visual displays. ording Devices: Introduction, Strip ntiometer type recorders, Bridge type recorders. Digital tape recording, Ulary recorders. Digital tape recording, Ulary recorders: At the end of the course. Measure resistance, inductance and explain the working of various metal. | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder e the student will capacitance using ters used for mea | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E be able to: g bridges and determine ear | candescent, Fluorescent, s, Null balance recorders, nart CG) ■ |
| lays. Cathode ray tubes, Light emitting tid vapour and Visual displays. ording Devices: Introduction, Strip entiometer type recorders, Bridge type recorders. Digital tape recording, Ul ary recorders. At the end of the course Measure resistance, inductance and explain the working of various metadjustments, calibration & errors in entire entite entire entire entire entire entire entire e | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder e the student will capacitance using ters used for mea energy meters. | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E be able to: g bridges and determine ear asurement of Power, Ener | candescent, Fluorescent, s, Null balance recorders, nart CG) ■ rth resistance. gy & understand the |
| lays. Cathode ray tubes, Light emitting tid vapour and Visual displays. ording Devices: Introduction, Strip ntiometer type recorders, Bridge type recorders. Digital tape recording, Ulary recorders. Digital tape recording, Ulary recorders: At the end of the course Measure resistance, inductance and e Explain the working of various metal | g diodes, Liquid chart recorders, ecorders, LVDT traviolet recorder e the student will capacitance using ters used for mea energy meters. he range of instru | crystal displays, Nixes, In Galvanometer recorders type recorders, Circular ch s. Electro Cardio Graph (E be able to: g bridges and determine ear asurement of Power, Energy ments & instrument transf | candescent, Fluorescent, s, Null balance recorders, nart CG) ■ rth resistance. gy & understand the |

- Explain the working of different electronic instruments.
- Explain the working of different display and recording devices.

| | CTRICAL AND ELECTR edit System (CBCS) and O | ONICS ENGINEERING utcome Based Education (C | (BE) |
|--|--|---|------------------------------------|
| Choice Dascu Civ | SEMESTER - | | JE) |
| COMPLEX ANA | | ND STATISTICAL METH | IODS |
| | (Common to all prog | | |
| Course Code | 18MAT41 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (2:2:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| functions arising in potentTo develop probability | ial theory, quantum mechan distribution of discrete, co | variables, conformal mappin ics, heat conduction and field ntinuous random variables a ign engineering and microwa | I theory. and joint probability |
| Module-1 | | | |
| Calculus of complex function differentiability. Analytic funct consequences. Construction of analytic function | ions: Cauchy-Riemann e | quations in Cartesian and | |
| Module-2 | | | |
| Conformal transformations: Intr | roduction. Discussion of | | |
| transformations: $w = Z^2$, $w = e^z$, | $w = z + \frac{1}{2}, (z \neq 0)$.Bilinear | transformations- Problems. | |
| and problems. Module-3 Probability Distributions: Revie probability mass/density function | s. Binomial, Poisson, expo | nential and normal distribut | |
| derivation for mean and standard | deviation)-Illustrative examp | ples. | |
| Module-4 | | | |
| Statistical Methods: Correlation -problems. Regression analysis- li Curve Fitting: Curve fitting by th $y = ax + b$, $y = ax^b$ and $y = ax^b$ | nes of regression –problems ne method of least squares- f | | nd rank correlation |
| Module-5 | | | |
| Joint probability distribution: J | Joint Probability distribution | n for two discrete random va | ariables, expectation |
| and covariance. | | | |
| Sampling Theory: Introduction the hypothesis for means, student's t- | distribution, Chi-square di | stribution as a test of goodne | |
| Course Outcomes: At the end of | | | |
| electromagnetic field theo | ry. | otentials to solve the problem | C |
| visualization and image p | rocessing. | gral arising in aerofoil theor | |
| engineering field. | | is in analyzing the probability | |
| • Make use of the correlation statistical data. | on and regression analysis to | fit a suitable mathematical n | nodel for the |
| | 41 | | |

• Construct joint probability distributions and demonstrate the validity of testing the hypothesis.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - IV

| POWER GENERATION AND ECONOMICS | | | |
|--------------------------------|--------|------------|----|
| Subject Code | 18EE42 | CIE Marks | 40 |
| Number of Lecture Hours/Week | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course Learning Objectives:

- Explain the arrangement and operation of hydroelectric, steam, diesel, gas turbine and nuclear power plants and working of major equipment in the plants.
- Classification of substation and explain the operation of different substation equipment.
- Explain the importance of grounding and different grounding methods used in practice.
- Explain the economics of power generation and importance of power factor. ■

Module-1

Hydroelectric Power Plants: Hydrology, run off and stream flow, hydrograph, flow duration curve,

Mass curve, reservoir capacity, dam storage. Hydrological cycle, merits and demerits of hydroelectric power plants, Selection of site. General arrangement of hydel plant, elements of the plant, Classification of the plants based on water flow regulation, water head and type of load the plant has to supply. Water turbines – Pelton wheel, Francis, Kaplan and propeller turbines. Characteristic of water turbines Governing of turbines, selection of water turbines. Underground, small hydro and pumped storage plants. Choice of size and number of units, plant layout and auxiliaries. ■

Module-2

Steam Power Plants: Introduction, Efficiency of steam plants, Merits and demerits of plants, selection of site. Working of steam plant, Power plant equipment and layout, Steam turbines, Fuels and fuel handling, Fuel combustion and combustion equipment, Coal burners, Fluidized bed combustion, Combustion control, Ash handling, Dust collection, Draught systems, Feed water, Steam power plant controls, plant auxiliaries.

Diesel Power Plant: Introduction, Merits and demerits, selection site, elements of diesel power plant, applications.

Gas Turbine Power Plant: Introduction Merits and demerits, selection site, Fuels for gas turbines, Elements of simple gas turbine power plant, Methods of improving thermal efficiency of a simple steam power plant, Closed cycle gas turbine power plants. Comparison of gas power plant with steam **Module-3**

Nuclear Power Plants: Introduction, Economics of nuclear plants, Merits and demerits, selection of site, Nuclear reaction, Nuclear fission process, Nuclear chain reaction, Nuclear energy, Nuclear fuels, Nuclear plant and layout, Nuclear reactor and its control, Classification of reactors, power reactors in use, Effects of nuclear plants, Disposal of nuclear waste and effluent, shielding. ■

Module-4

Substations: Introduction to Substation equipment; Transformers, High Voltage Fuses, High Voltage Circuit Breakers and Protective Relaying, High Voltage Disconnect Switches, Lightning Arresters, High Voltage Insulators and Conductors, Voltage Regulators, Storage Batteries, Reactors, Capacitors, Measuring Instruments, and power line carrier communication equipment. Classification of substations – indoor and outdoor, Selection of site for substation, Bus-bar arrangement schemes and single line diagrams of substations. ■

Substations (continued): Interconnection of power stations. Introduction to gas insulated substation, Advantages and economics of Gas insulated substation.

Grounding: Introduction, Difference between grounded and ungrounded system. System grounding – ungrounded, solid grounding, resistance grounding, reactance grounding, resonant grounding. Earthing transformer. Neutral grounding and neutral grounding transformer. ■

Module-5

Economics: Introduction, Effect of variable load on power system, classification of costs, Cost analysis. Interest and Depreciation, Methods of determination of depreciation, Economics of Power generation, different terms considered for power plants and their significance, load sharing. Choice of size and number of generating plants. Tariffs, objective, factors affecting the tariff, types. Types of consumers and their tariff. Power factor, disadvantages, causes, methods of improving power factor, Advantages of improved power factor, economics of power factor improvement and comparison of methods of improving the power factor. Choice of equipment.

- Describe the working of hydroelectric, steam, nuclear power plants and state functions of major equipment of the power plants.
- Classify various substations and explain the functions of major equipments in substations.
- Explain the types of grounding and its importance.
- Infer the economic aspects of power system operation and its effects.
- Explain the importance of power factor improvement.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - IV

| TRANSMISSION AND DISTRIBUTION | | | | |
|-------------------------------|--------|------------|----|--|
| Course Code | 18EE43 | CIE Marks | 40 | |
| Number of Lecture Hours/Week | 3:2:0 | SEE Marks | 60 | |
| Credits | 04 | Exam Hours | 03 | |

Course Learning Objectives:

- To understand the concepts of various methods of generation of power.
- To understand the importance of HVAC, EHVAC, UHVAC and HVDC transmission.
- To design insulators for a given voltage level.
- To calculate the parameters of the transmission line for different configurations and assess the performance of the line.
- To study underground cables for power transmission and evaluate different types of distribution systems. ■

Module-1

Introduction to Power System: Structure of electric power system: generation, transmission and distribution. Advantages of higher voltage transmission: HVAC, EHVAC, UHVAC and HVDC. Interconnection. Feeders, distributors and service mains.

Overhead Transmission Lines: A brief introduction to types of supporting structures and line conductors-Conventional conductors; Aluminium Conductor steel reinforced (ACSR), All – aluminium alloy conductor (AAAC) and All –aluminium conductor (AAC). High temperature conductors; Thermal resistant aluminium alloy (ATI),Super thermal resistant aluminium alloy (ZTAI), Gap type thermal resistant aluminium alloy conductor steel reinforced (GTACSR), Gap type super thermal resistant aluminium alloy conductor steel reinforced (GZTACSR). Bundle conductor and its advantages. Importance of sag, Sag calculation – supports at same and different levels, effect of wind and ice. Line vibration and vibration dampers. Overhead line protection against lightening; ground wires.

Overhead L ine Insulators: A brief introduction to types of insulators, material used-porcelain, toughened glass and polymer (composite). Potential distribution over a string of suspension insulators. String efficiency, Methods of increasing string efficiency. Arcing horns.

Module-2

Line Parameters: Introduction to line parameters- resistance, inductance and capacitance. Calculation of inductance of single phase and three phase lines with equilateral spacing, unsymmetrical spacing, double circuit and transposed lines. Inductance of composite – conductors, geometric mean radius (GMR) and geometric mean distance (GMD). Advantages of single circuit and double circuit lines.). Calculation of capacitance of single phase and three phase lines with equilateral spacing, unsymmetrical spacing, double circuit and transposed lines. Capacitance of composite – conductor, geometric mean radius (GMR) and geometric mean distance (GMD). Advantages of single circuit and transposed lines. Capacitance of composite – conductor, geometric mean radius (GMR) and geometric mean distance (GMD). Advantages of single circuit and double circuit lines. ■

Module-3

Performance of Transmission Lines: Classification of lines – short, medium and long. Current and voltage relations, line regulation and Ferranti effect in short length lines, medium length lines considering Nominal T and nominal circuits, and long lines considering hyperbolic form equations. Equivalent circuit of a long line. ABCD constants in all cases. ■

Module-4

Corona: Phenomena, disruptive and visual critical voltages, corona loss. Advantages and disadvantages of corona. Methods of reducing corona.

Underground Cable: Types of cables, constructional features, insulation resistance, thermal rating, charging current, grading of cables – capacitance and inter-sheath. Dielectric loss. Comparison between ac and DC cables. Limitations of cables. Specification of power cables. ■

Module-5

Distribution: Primary AC distribution systems – Radial feeders, parallel feeders, loop feeders and interconnected network system. Secondary AC distribution systems – Three phase 4 wire system and single phase 2 wire distribution, AC distributors with concentrated loads. Effect of disconnection of neutral in a 3 phase four wire system.

Reliability and Quality of Distribution System: Introduction, definition of reliability, failure, probability concepts, limitation of distribution systems, power quality, Reliability aids.

- Explain transmission and distribution scheme, identify the importance of different transmission systems and types of insulators.
- Analyze and compute the parameters of the transmission line for different configurations.
- Assess the performance of overhead lines.
- Interpret corona, explain the use of underground cables.
- Classify different types of distribution systems; examine its quality & reliability.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) **SEMESTER - IV ELECTRIC MOTORS** Course Code **18EE44** CIE Marks 40 Number of Lecture Hours/Week SEE Marks 3:0:0 60 Credits 03 Exam Hours 03 **Course Learning Objectives:** • To study the constructional features of Motors and select a suitable drive for specific application. • To study the constructional features of Three Phase and Single phase induction Motors. • To study different test to be conducted for the assessment of the performance characteristics of motors. • To study the speed control of motor by a different methods. • Explain the construction and operation of Synchronous motor and special motors. Module-1 DC Motors: Classification, Back emf, Torque equation, and significance of back emf. Characteristics of shunt, series & compound motors. Speed control of shunt, series and compound motors. Application of motors. DC motor starters - 3 point and 4 point. Losses and Efficiency- Losses in DC motors, power flow diagram, efficiency, condition for maximum efficiency. Module-2 Testing of DC Motors: Direct & indirect methods of testing of DC motors-Brake test, Swinburne's test, Retardation test, Hopkinson's test, Field's test, merits and demerits of tests. Three Phase Induction Motors: Review of concept and generation of rotating magnetic field, Principle of operation, construction, classification and types; squirrel-cage, slip-ring (No question shall be set from the review portion). Slip, Torque equation, torque-slip characteristic covering motoring, generating and braking regions of operation, Maximum torque, significance of slip. Module-3 Performance of Three-Phase Induction Motor: Phasor diagram of induction motor on no-load and on load, equivalent circuit, losses, efficiency, No-load and blocked rotor tests. Performance of the motor from the circle diagram and equivalent circuit. Cogging and crawling. High torque rotors-double cage and deep rotor bars. Equivalent circuit and performance evaluation of double cage induction motor. Induction motor working as induction generator. Module-4 Starting and Speed Control of Three-Phase Induction Motors: Need for starter. Direct on line, Star-Delta and autotransformer starting. Rotor resistance starting. Speed control by voltage, frequency, and rotor resistance methods Single-Phase Induction Motor: Double revolving field theory and principle of operation. Construction and operation of split-phase, capacitor start, capacitor run, and shaded pole motors. Comparison of single phase motors and applications. Module-5 Synchronous Motor: Principle of operation, phasor diagrams, torque and torque angle, Blondel diagram, effect of change in load, effect of change in excitation, V and inverted V curves. Synchronous condenser, hunting and damping. Methods of starting synchronous motors. Other Motors: Construction and operation of Universal motor, AC servomotor, Linear induction motor and stepper motors. ■ **Course Outcomes:** At the end of the course the student will be able to: Explain the construction, operation and classification of DC Motor, AC motor and Special purpose • motors. Describe the performance characteristics & applications of Electric motors. Demonstrate and explain the methods of testing of DC machines and determine losses and efficiency. Control the speed of DC motor and induction motor. Explain the starting methods, equivalent circuit and phasor diagrams, torque angle, effect of change in excitation and change in load, hunting and damping of synchronous motors.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - IV

| ELECTROMAGNETIC FIELD THEORY | | | | |
|------------------------------|--------|------------|----|--|
| Course Code | 18EE45 | CIE Marks | 40 | |
| Number of Lecture Hours/Week | 2:2:0 | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |

Course Learning Objectives:

- To study different coordinate systems for understanding the concept of gradient, divergence and curl of a vector.
- To study the application of Coulomb's Law and Gauss Law for electric fields produced by different charge configurations.
- To evaluate the energy and potential due to a system of charges.
- To study the behavior of electric field across a boundary between a conductor and dielectric and between two different dielectrics.
- To study the magnetic fields and magnetic materials.
- To study the time varying fields and propagation of waves in different media.

Module-1

Vector Analysis: Scalars and Vectors, Vector algebra, Cartesian co-ordinate system, Vector Components and unit vectors. Scalar field and Vector field. Dot product and Cross product, Gradient of a scalar field. Divergence and Curl of a vector field. Co – ordinate systems: cylindrical and spherical, relation between different coordinate systems. Expression for gradient, divergence and curl in rectangular, cylindrical and spherical co-ordinate systems. Numerical.

Electrostatics: Coulomb's law, Electric field intensity and its evaluation for (i) point charge (ii) line charge (iii) surface charge (iv) volume charge distributions. Electric flux density, Gauss law and its applications. Maxwell's first equation (Electrostatics). Divergence theorem. Numerical.

Module-2

Energy and Potential: Energy expended in moving a point charge in an electric field. The line integral. Definition of potential difference and potential. The potential field of a point charge and of a system of charges. Potential gradient. The dipole. Energy density in the electrostatic field. Numerical. **Conductor and Dielectrics:** Current and current density. Continuity of current. Metallic conductors, conductor's properties and boundary conditions. Perfect dielectric materials, capacitance calculations. Parallel plate capacitor with two dielectrics with dielectric interface parallel to the conducting plates. Numerical.

Module-3

Poisson's and Laplace Equations: Derivations and problems, Uniqueness theorem. **Steady magnetic fields:** Biot - Savart's law, Ampere's circuital law. The Curl. Stokes theorem. Magnetic flux and flux density. Scalar and vector magnetic potentials. Numerical.

Module-4

Magnetic forces: Force on a moving charge and differential current element. Force between differential current elements. Force and torque on a closed circuit. Numerical.

Magnetic Materials and Magnetism: Nature of magnetic materials, magnetisation and permeability. Magnetic boundary conditions. Magnetic circuit, inductance and mutual inductance. Numerical. ■

Module-5

Time Varying Fields and Maxwell's Equations: Faraday's law, Displacement current. Maxwell's equations in point form and integral form. Numerical.

Uniform plane wave: Wave propagation in free space and in dielectrics. Pointing vector and power considerations. Propagation in good conductors, skin effect. Numerical.■

- Use different coordinate systems, Coulomb's Law and Gauss Law for the evaluation of electric fields produced by different charge configurations.
- Calculate the energy and potential due to a system of charges & Explain the behavior of electric field across a boundary conditions.
- Explain the Poisson's, Laplace equations and behavior of steady magnetic fields.
- Explain the behavior of magnetic fields and magnetic materials.
- Asses time varying fields and propagation of waves in different media. ■

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - IV

OPERATIONAL AMPLIFIERS AND LINEAR ICs

| 01 Liwiii | | | |
|------------------------------|--------|------------|----|
| Course Code | 18EE46 | CIE Marks | 40 |
| Number of Lecture Hours/Week | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course Learning Objectives:

- To understand the basics of Linear ICs such as Op-amp, Regulator, Timer & PLL.
- To learn the designing of various circuits using linear ICs.
- To use these linear ICs for specific applications.
- To understand the concept and various types of converters.
- To use these ICs, in Hardware projects.

Module-1

Operational Amplifiers: Introduction, Block diagram representation of a typical Op-amp, schematic symbol, characteristics of an Op-amp, ideal op-amp, equivalent circuit, ideal voltage transfer curve, open loop configuration, differential amplifier, inverting & non –inverting amplifier, Op-amp with negative feedback(excluding derivations).

General Linear Applications: A.C. amplifier, summing, scaling & averaging amplifier, inverting and non-inverting configuration, Instrumentation amplifier. T1

Module-2

Active Filters: First & Second order high pass & low pass Butterworth filters. Band pass filters, all pass filters.

DC Voltage Regulators: voltage regulator basics, voltage follower regulator, adjustable output regulator, LM317 & LM337 Integrated circuits regulators. **T1**

Module-3

Signal Generators: Triangular / rectangular wave generator, phase shift oscillator, saw tooth oscillator.

Comparators & Converters: Basic comparator, zero crossing detector, inverting & non-inverting Schmitt trigger circuit, voltage to current converter with grounded load, current to voltage converter and basics of voltage to frequency and frequency to voltage converters. **T1**

Module-4

Signal processing circuits: Precision half wave & full wave rectifiers

A/D & D/A Converters: Basics, R–2R D/A Converter, Integrated circuit 8-bit D/A, successive approximation ADC, linear ramp ADC R1

Module-5

Phase Locked Loop (PLL): Basic PLL, components, performance factors. Timer: Internal architecture of 555 timer, Mono stable multivibrators and applications. T1

- Describe the characteristics of ideal and practical operational amplifier.
- Design filters and signal generators using linear ICs.
- Demonstrate the application of Linear ICs as comparators and rectifiers.
- Analyze voltage regulators for given specification using op-amp and IC voltage regulators.
- Summarize the basics of PLL and Timer.

| Outcome Based Ed | lucation (OBE) and C | | |
|---|--|---|--|
| | SEMESTE | | |
| | ADDITIONAL MATH | | 、 、 |
| (Mandato) (A Bridge course for Later) | ry Learning Course: Co al Entry students under | | |
| Course Code | 18MATDIP41 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (2:1:0) | SEE Marks | 60 |
| Credits | 0 | Exam Hours | 03 |
| Course Learning Objectives: | · | | |
| | cepts of linear algebra, s | second & higher ord | er differential equations along |
| with methods to solve them. | | C C | |
| • To provide an insight into | o elementary probability | theory and numeric | cal methods. |
| Module-1 | | | |
| Linear Algebra: Introduction - rar | nk of matrix by elemen | tary row operations | - Echelon form. Consistency o |
| system of linear equations - Gauss | elimination method. I | Eigen values and Ei | igen vectors of a square matrix |
| Problems. | | | |
| Module-2 | | | |
| Numerical Methods: Finite differ difference formulae (Statements of | only)-problems. Solution | on of polynomial a | and transcendental equations - |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falsi Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear dif coefficients. Homogeneous /non-h | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. | on of polynomial a llae)- Illustrative ex Problems. second and higher | and transcendental equations camples. Numerical integration order equations with constant |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falst Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-here <i>restricted to</i> $R(x)=e^{ax}$, sin <i>ax</i> /cos <i>ax</i> | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. | on of polynomial a llae)- Illustrative ex Problems. second and higher | and transcendental equations camples. Numerical integration order equations with constant |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falst Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-he <i>restricted to</i> $R(x)=e^{ax}$, sin ax /cos ax Module-4 | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. for f(D)y = R(x).] DE's):- Formation of neous PDE by direct in | on of polynomial a llae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina | and transcendental equations - camples. Numerical integration order equations with constant operators.[Particular Integra |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falst Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-herestricted to $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(P functions. Solution of non-homogeneous /non-homogeneous/ | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. for f(D)y = R(x).] DE's):- Formation of neous PDE by direct in | on of polynomial a llae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina | and transcendental equations - camples. Numerical integration order equations with constant operators.[Particular Integra |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Fals: Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear dif coefficients. Homogeneous /non-ho- <i>restricted to</i> $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(P) functions. Solution of non-homogen with respect to one independent variation Module-5 Probability: Introduction. Sample | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. for $f(D)y = R(x)$.] DE's):- Formation of neous PDE by direct in table only. | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. 4 | and transcendental equations - camples. Numerical integration order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative |
| Numerical Methods: Finite difference formulae (Statements of Newton-Raphson and Regula-Fals: Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear differential to $R(x) = e^{ax}$, sin $ax / \cos ax$ Module-4 Partial Differential Equations(P) functions. Solution of non-homogen with respect to one independent vari Module-5 Probability: Introduction. Sample theorems. Conditional probability, F | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. for f(D)y = R(x).] DE's):- Formation of neous PDE by direct in table only. space and events. Axio Bayes's theorem, proble | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. A ms. | and transcendental equations - camples. Numerical integration order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Fals: Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-herestricted to $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(Pf functions. Solution of non-homogen with respect to one independent variation Module-5 Probability: Introduction. Sample theorems. Conditional probability, F | only)-problems. Solution i methods (only formule's rule (without proof) ferential equations of omogeneous equations. for f(D)y = R(x).] DE's):- Formation of neous PDE by direct in iable only. space and events. Axio Bayes's theorem, proble | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. A ms. 1 be able to: | and transcendental equations - camples. Numerical integration order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falst Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-her restricted to $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(Pf functions. Solution of non-homogen with respect to one independent vari Module-5 Probability: Introduction. Sample theorems. Conditional probability, F Course Outcomes: At the end of th CO1: Solve systems of linear equati | only)-problems. Solution i methods (only formu- le's rule (without proof) ferential equations of omogeneous equations. for $f(D)y = R(x)$.] DE's):- Formation of neous PDE by direct in iable only. space and events. Axio Bayes's theorem, proble | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. A ms. 1 be able to: a. | and transcendental equations - camples. Numerical integration r order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative Addition & multiplication |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Fals: Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-her <i>restricted to</i> $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(PI functions. Solution of non-homogen with respect to one independent vari Module-5 Probability: Introduction. Sample theorems. Conditional probability, H Course Outcomes: At the end of th CO1: Solve systems of linear equati CO2: Apply the knowledge of nume | only)-problems. Solution i methods (only formu- le's rule (without proof) ferential equations of omogeneous equations. <i>for</i> $f(D)y = R(x)$.] DE's):- Formation of neous PDE by direct in iable only. space and events. Axio Bayes's theorem, proble | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. A ms. 1 be able to: a. ling and solving eng | and transcendental equations - camples. Numerical integration r order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative Addition & multiplication |
| Numerical Methods: Finite differ difference formulae (Statements of Newton-Raphson and Regula-Falst Simpson's one third rule and Weddl Module-3 Higher order ODE's: Linear diff coefficients. Homogeneous /non-her restricted to $R(x)=e^{ax}$, sin ax /cos ax Module-4 Partial Differential Equations(Pf functions. Solution of non-homogen with respect to one independent vari Module-5 Probability: Introduction. Sample theorems. Conditional probability, F Course Outcomes: At the end of th CO1: Solve systems of linear equati | only)-problems. Solution i methods (only formu- le's rule (without proof) ferential equations of omogeneous equations. <i>for</i> $f(D)y = R(x)$.] DE's):- Formation of neous PDE by direct in table only. space and events. Axio Bayes's theorem, proble | on of polynomial a lae)- Illustrative ex Problems. second and higher Inverse differentia PDE's by elimina tegration. Homoger ms of probability. A ms. I be able to: a. ling and solving eng differential equation | and transcendental equations - camples. Numerical integration r order equations with constant al operators.[Particular Integration tion of arbitrary constants and neous PDEs involving derivative Addition & multiplication |

IV SEMESTER DETAILED SYLLABUS

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - V

| | SEMESTER - V | | | |
|--------------------------------------|--------------|------------|----|--|
| MANAGEMENT AND ENTREPRENEURSHIP | | | | |
| Course Code | 18EE51 | CIE Marks | 40 | |
| Number of Lecture Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |

Course Learning Objectives:

- To introduce the field of management, task of the manager, importance of planning and types of planning, staff recruitment and selection process.
- To discuss the ways in which work is allocation, structure of organizations, modes of communication and importance of managerial control in business.
- To explain need of coordination between the manager and staff, the social responsibility of business and leadership.
- To explain the role and importance of the entrepreneurine conomic development and the concepts of entrepreneurship.
- To explain various types of entrepreneurs and their functions, the myths of entrepreneurship and the factors required for capacity building for entrepreneurs
- To discuss theimportance of SmallScaleIndustries and the related terms and problems involved.
- To discuss methods for generatingnewbusinessideasandbusinessopportunitiesinIndiaandtheimportance of business plan.
- To introduce the concepts of project management and discuss capitol building process.
- To explain project feasibility study and project appraisal anddiscuss project financing
- To discuss about different institutions at state and central levels supporting business enterprises. ■

Module-1

Management: Definition, Importance – Nature and Characteristics of Management, Management Functions, Roles of Manager, Levels of Management, Managerial Skills, Management & Administration, Management as a Science, Art &Profession. Planning: Nature, Importance and Purpose Of Planning, Types of Plans, Steps in Planning, Limitations

of Planning, Decision Making – Meaning, Types of Decisions- Steps in Decision Making.

Module-2

Organizing and Staffing: Meaning, Nature and Characteristics of Organization – Process of Organization, Principles of Organization, Departmentalization, Committees – meaning, Types of Committees, Centralization Versus Decentralization of Authority and Responsibility, Span of Control (Definition only), Nature and Importance of Staffing, Process of Selection and Recruitment.

Directing and Controlling: Meaning and Nature of Directing-Leadership Styles, Motivation Theories Communication – Meaning and Importance, Coordination- Meaning and Importance, Techniques of Coordination. Controlling – Meaning, Steps in Controlling.

Module-3

Social Responsibilities of Business: Meaning of Social Responsibility, Social Responsibilities of Business towards Different Groups, Social Audit, Business Ethics and Corporate Governance. **Entrepreneurship**: Definition of Entrepreneur, Importance of Entrepreneurship, concepts of Entrepreneurship, Characteristics of successful Entrepreneur, Classification of Entrepreneurs, Intrapreneur – An Emerging Class, Comparison between Entrepreneur and Intrapreneur, Myths of Entrepreneurship, Entrepreneurial Development models, Entrepreneurial development cycle, Problems faced by Entrepreneurs and capacity building for

Module-4

Modern Small Business Enterprises: Role of Small Scale Industries, Concepts and definitions of SSI

Enterprises, Government policy and development of the Small Scale sector in India, Growth and Performance of Small Scale Industries in India, Sickness in SSI sector, Problems for Small Scale Industries, Impact of Globalization on SSI, Impact of WTO/GATT on SSIs, Ancillary Industry and Tiny Industry (Definition only).

Institutional Support for Business Enterprises: Introduction, Policies & Schemes of Central–Level Institutions, State-Level Institutions. ■

Module-5

Project Management: Meaning of Project, Project Objectives & Characteristics, Project Identification-Meaning & Importance; Project Life Cycle, Project Scheduling, Capital Budgeting, Generatin g an Investment Project Proposal, Project Report-Need and Significance of Report, Contents, Formulation, Project Analysis-Market, Technical, Financial, Economic, Ecological, Project Evaluation and Selection, Project Financing, Project Implementation Phase, Human & Administrative aspects of Project Management, Prerequisites for Successful Project Implementation.

New Control Techniques- PERT and CPM, Steps involved in developing the network, Uses and Limitations of PERT and CPM .■

- **Course Outcomes:** At the end of the course the student will be able to:
 - Explain the field of management, task of the manager, planning and steps in decision making.
 - Discuss the structure of organization, importance of staffing, leadership styles, modes of communication, techniques of coordination and importance of managerial control in business.
 - Explain the concepts of entrepreneurship and a businessman's social responsibilities towards different groups.
 - Show an understanding of role of SSI's in the development of country and state/central level institutions/agencies supporting business enterprises.
 - Discuss the concepts of project management, capital budgeting, project feasibility studies, need for project report and new control techniques.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - V

| MICROCONTROLLER | | | | |
|--------------------------------------|--------|------------|----|--|
| Course Code | 18EE52 | CIE Marks | 40 | |
| Number of Lecture Hours/Week (L:T:P) | 3:2:0 | SEE Marks | 60 | |
| Credits | 04 | Exam Hours | 03 | |

Course Learning Objectives:

- To explain the internal organization and working of Computers, microcontrollers and embedded processors.
- Compare and contrast the various members of the 8051 family.
- To explain the registers of the 8051 microcontroller, manipulation of data using registers and MOV instructions.
- To explain in detail the execution of 8051 Assembly language instructions and data types
- To explain loop, conditional and unconditional jump and call, handling and manipulation ofI/O instructions.
- To explain different addressing modes of 8051, arithmetic, logic instructions, and programs.
- To explain develop 8051C programs for time delay, I/O operations, I/O bit manipulation, logic,

Module-1

8051 Microcontroller Basics: Inside the Computer, Microcontrollers and Embedded Processors, Block Diagram of 8051, PSW and Flag Bits, 8051 Register Banks and Stack, Internal Memory Organization of 8051, IO Port Usage in 8051, Types of Special Function Registers and their uses in 8051, Pins Of 8051. Memory Address Decoding, 8031/51 Interfacing With External ROM And RAM.8051 Addressing

Modes.

Module-2

Assembly Programming and Instruction of 8051: Introduction to 8051 assembly programming, Assembling and running an 8051 program, Data types and Assembler directives, Arithmetic, logic instructions and programs, Jump, loop and call instructions, IO port programming.

Module-3

8051 Programming in C: Data types and time delay in 8051C, IO programming in 8051C, Logic operations in 8051 C, Data conversion program in 8051 C, Accessing code ROM space in 8051C, Data serialization using 8051C

8051 Timer Programming in Assembly and C: Programming 8051 timers, Counter programming, Programming timers 0 and 1 in 8051 C. ■

Module-4

8051 Serial Port Programming in Assembly and C: Basics of serial communication, 8051 connection to RS232, 8051 serial port programming in assembly, serial port programming in 8051 C.

8051 Interrupt Programming in Assembly and C: 8051 interrupts, Programming timer, external hardware, serial communication interrupt, Interrupt priority in 8051/52, Interrupt programming in C. ■ Module-5

Interfacing: LCD interfacing, Keyboard interfacing.

ADC, DAC and Sensor Interfacing: ADC 0808 interfacing to 8051, Serial ADC Max1112 ADC interfacing to 8051, DAC interfacing, Sensor interfacing and signal conditioning.

Motor Control: Relay, PWM, DC and Stepper Motor: Relays and opt isolators, stepper motor interfacing, DC motor interfacing and PWM.

8051 Interfacing with 8255: Programming the 8255, 8255 interfacing, C programming for 8255. ■

- Outline the 8051 architecture, registers, internal memory organization, addressing modes.
- Discuss 8051 addressing modes, instruction set of 8051, accessing data and I/O port programming.
- Develop 8051C programs for time delay, I/O operations, I/O bit manipulation, logic and arithmetic operations, data conversion and timer/counter programming.
- Summarize the basics of serial communication and interrupts, also develop 8051 programs for serial data communication and interrupt programming.
- Program 8051 to work with external devices for ADC, DAC, Stepper motor control, DC motor control, Elevator control.■

| B. E. ELECTRICA | L AND ELEC | TRONICS ENGINEER | ING |
|--|---|---|--|
| Choice Based Credit Syste | | d Outcome Based Educat | |
| D | OWER ELEC | | |
| Course Code | 18EE53 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P) | 3:2:0 | SEE Marks | 60 |
| Credits | 04 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| To give an overview of applications their switching characteristics. To explain power diode characterist circuits. To explain the techniques for design | ics, types, their | operation and the effects of | f power diodes on RL |
| To explain different power transiste To explain different types of Thyris To explain the design, analysis tech rectifiers, DC- DC, DC -AC convert | ors, their steady stors, their gate niques, perform | state and switching charac characteristics and gate co nance parameters and char | eteristics and imitations. ntrol requirements. |
| Module-1 | | | |
| Introduction: Applications of Power E Effects, Characteristics and Specifications Power Diodes: Introduction, Diode Ch Types, Silicon Carbide Diodes, Silicon Ca with RL load. Diode Rectifiers: Introduction, Diode Ch Full-Wave Rectifiers with R load, Single- | of Switches. haracteristics, I arbide Schottky ircuits with DC | Reverse Recovery Chara Diodes, Freewheeling did Source connected to R a | cteristics, Power Diode odes ,Freewheeling diodes nd RL load, Single-Phase |
| Module-2 | | | |
| Power Transistors: Introduction, Pow Characteristics Bipolar Junction Transis Switching Limits, IGBTs, MOSFET Gate Pulse transformers and Opto-couplers.■ Module-3 Thyristors: Introduction, Thyristor Char | tors – Steady e Drive, BJT Ba f 1 acteristics, Two | State Characteristics, S ase Drive, Isolation of Ga | witching Characteristics, te and Base Drives, vristor, Thyristor Turn- |
| On, Thyristor Turn-Off, A brief study Operation of Thyristors, di/dt Protection, Transistor. \blacksquare T1 | on Thyristor <i>dv/dt</i> Protection | Types, Series Operation n, DIACs, Thyristor Firin | of Thyristors, Parallel g Circuits, Unijunction |
| Module-4 | | | |
| Controlled Rectifiers: Introduction, Sin circuit with RL Load and Freewheeling I Full Converters with RLE Load, Single-I Converters. | Diode, Single p Phase Dual Con | hase half wave circuit wit nverters, Principle of oper | h RLE Load, Single-Phase ation of Three- Phase due |
| AC Voltage Controllers: Introduction, | Principle of pl | ase control & Integral cy | ycle control, Single-Phase |
| Full-Wave Controllers with Resistive Le | oads, Single- ¹ | Phase Full-Wave Controll | ers with Inductive Loads |
| Three-Phase Full-Wave Controllers. \blacksquare T | 1 & R1 | | |
| Module-5 | | | |
| DC-DC Converters: Introduction, principerformance parameters, DC-DC converter DC-AC Converters : Introduction, principinverters, voltage control of single phase in | er classification ple of operation | • single phase bridge invert | ters, three phase bridge |
| Course Outcomes. At the and of the | the student - | will be able to: | |
| Course Outcomes: At the end of the course of applications their switching characteristics, power diodes on RL circuits. To explain the techniques for design the techniques for design | power electronic er diode charact and analysis of s | cs, different types of power eristics, types, their operatio single phase diode rectifier o | n and the effects of power circuits. |
| To explain different power transistor | s, their steady sta | ate and switching characteria | stics and limitations. |

- To explain different power transistors, their steady state and switching characteristics and limitations. • To explain different types of Thyristors, their gate characteristics and gate control requirements.
- To explain the design, analysis techniques, performance parameters and characteristics of controlled rectifiers, DC-DC, DC -AC converters and Voltage controllers.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - V

SIGNALS AND SYSTEMS

| L. L | | | |
|--|--------|------------|----|
| Course Code | 18EE54 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course Learning Objectives:

- To discuss arising of signals in different systems.
- To classify the signals and define certain elementary signals.
- To explain basic operations on signals and properties of systems.
- To explain the use of convolution integral and convolution summation in analyzing the response of linear time invariant systems in continuous and discrete time domains.
- To explain the properties of linear time invariant systems in terms of impulse response description.
- To explain determination of response of a given linear time invariant system and to provide a block diagram representation to it.
- To explain Fourier transform representation of continuous time and discrete time non –periodic signals and the properties of Fourier Transforms.
- To explain the applications of Fourier transform representation to study signals and linear time invariant systems. To explain the use of Z-transform in the complex exponential representation of discrete time signals and the analysis of systems.

Module-1

Introduction: Definitions of signals and a system, classification of signals, basic operations on signals. Elementary signals viewed as interconnections of operations, properties of systems.

Module-2

Time – Domain Representations for LTI Systems: Convolution, impulse response, properties, solution of differential and difference equations, block diagram representation.

Module-3

The Continuous-Time Fourier Transform: Representation of a non -periodic signals: continuous-time Fourier transform (FT), Properties of continuous-time Fourier transform, Applications. Frequency response of LTI systems, Solutions of differential equations.

Module-4

The Discrete-Time Fourier Transform: Representations of non-periodic signals: The discrete-time Fourier transform (DTFT), Properties of DTFT and applications. Frequency response of LTI system, Solutions of difference equations.

Module-5

Z-Transforms: Introduction, Z-transform, properties of ROC, properties of Z-transforms, inversion of Z-transform methods - power series and partial expansion, Transforms analysis of LTI systems, transfer function, stability and causality, unilateral Z-transform and its application to solve difference equations.

- Explain the generation of signals, behavior of system and the basic operations that can be performed on signals and properties of systems.
- Apply convolution in both continuous and discrete domain for the analysis of systems given impulse response of a system.
- Solve the continuous time and discrete time systems by various methods and their representation by block diagram.
- Perform Fourier analysis for continuous and discrete time, linear time invariant systems.
- Apply Z-transform and properties of Z transform for the analysis of discrete time systems.

| B. E. ELECTRICAI | L AND ELECT | FRONICS ENGINE | ERING | |
|---|---|---|--|--|
| Choice Based Credit System | m (CBCS) and | Outcome Based Edu | | |
| SEMESTER - V | | | | |
| ELECTRICAL MACHINE DESIGN (Core Course) | | | | |
| Course Code | 18EE55 | CIE Marks | 40 | |
| Number of Lecture Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 | |
| Credits Course Learning Objectives: | 03 | Exam Hours | 03 | |
| To discuss design factors, limitation electrical machines. To discuss the properties of electrica electrical machines. | al, magnetic and | insulating materials u | used in the design of | |
| To derive the output equation of DC motor and synchronous machines. To discuss the selection of specific 1 To discuss separation of main dimer To discuss design of field windings | oadings, for var | ious machines. ent electrical machines | 5 | |
| performance parameters of transform | | | connest. 10 evaluate the | |
| To design of cooling tubes for the tra | | | | |
| To explain design of rotor of squirre | | | ·• | |
| To define short circuit ratio and disc | • | | a 🔳 | |
| Module-1 | | | | |
| Fundamental Aspects of Electrical Limitations in design, Modern Trends in de Electrical Engineering Materials: Desire Copper wires. Ferromagnetic Materials: S and Strip, Cold Rolled Grain Oriented S and Insulating Materials, Classification of Module-2 Design of DC Machines: Output Equation of Poles, Main Dimensions of armature, Estimation of Ampere Turns for the Magn of Shunt and Series Field Windings. ■ Module-3 | esign, manufact abilities of Cor Soft Magnetic n teel. Insulating Insulating mate n, Choice of Sp Design of Arm | uring Techniques. ducting Materials, Conterials – Solid Con- Materials: Desirable rials based on Therma ecific Loadings and Cature Slot Dimension | omparison of Aluminium an e Materials, Electrical Shee Properties, Temperature Ris Il Consideration. Choice of Number as, Commutator and Brushes | |
| Design of Transformers: Output Equati | | | | |
| Specific Loadings, Expression for Volts/T the Core, Estimation of Number of Turns Windings, No Load Current. Expression concentric coils, and calculation of Vo Rectangular) Tubes.■ | Furn, Determina s and Conducto n for the Leak | ation of Main Dimens or Cross Sectional are cage Reactance of | sions of ea of Primary and Secondar core type transformer wit | |
| Specific Loadings, Expression for Volts/T the Core, Estimation of Number of Turns Windings, No Load Current. Expression concentric coils, and calculation of Vo Rectangular) Tubes. ■ Module-4 | Furn, Determina s and Conducto n for the Leak oltage Regulati | ation of Main Dimens or Cross Sectional are cage Reactance of on. Design of Tank | sions of ea of Primary and Secondar core type transformer wit and Cooling (Round an | |
| Specific Loadings, Expression for Volts/T the Core, Estimation of Number of Turns Windings, No Load Current. Expression concentric coils, and calculation of Vo Rectangular) Tubes.■ | Furn, Determina s and Conducto n for the Leak oltage Regulati s: Output Equat ts and Winding of Rotor Bars ar | ation of Main Dimens or Cross Sectional are cage Reactance of on. Design of Tank ion, Choice of Specifi , Choice of Length Ai | sions of ea of Primary and Secondar core type transformer wit a and Cooling (Round an c Loadings, Main ir Gap, Estimation of Numbe | |
| Specific Loadings, Expression for Volts/T the Core, Estimation of Number of Turns Windings, No Load Current. Expression concentric coils, and calculation of Vo Rectangular) Tubes. ■ Module-4 Design of Three Phase Induction Motors Dimensions of Stator. Design of stator slow of Slots for Squirrel Cage Rotor. Design of | Furn, Determina s and Conducto n for the Leak oltage Regulati s: Output Equat ts and Winding of Rotor Bars ar | ation of Main Dimens or Cross Sectional are cage Reactance of on. Design of Tank ion, Choice of Specifi , Choice of Length Ai | sions of ea of Primary and Secondar core type transformer wit a and Cooling (Round an c Loadings, Main ir Gap, Estimation of Numbe | |
| Specific Loadings, Expression for Volts/T the Core, Estimation of Number of Turns Windings, No Load Current. Expression concentric coils, and calculation of Vo Rectangular) Tubes. ■ Module-4 Design of Three Phase Induction Motors Dimensions of Stator. Design of stator slow of Slots for Squirrel Cage Rotor. Design of of No Load Current and Leakage Reactance | Furn, Determina s and Conducto n for the Leak oltage Regulati s: Output Equat ts and Winding of Rotor Bars ar e. ■ Machines: Output | ation of Main Dimens or Cross Sectional are cage Reactance of on. Design of Tank ion, Choice of Specifi , Choice of Length Ai ad End Ring. Design | sions of ea of Primary and Secondar core type transformer wit a and Cooling (Round an c Loadings, Main ir Gap, Estimation of Numbe of Slip Ring rotor. Estimatio | |

- Identify and list, limitations, modern trends in design, manufacturing of electrical machines and properties of materials used in the electrical machines.
- Derive the output equation of DC machine, discuss selection of specific loadings and magnetic circuits of DC machines, design the field windings of DC machine, and design stator and rotor circuits of a DC machine.
- Derive the output equations of transformer, discuss selection of specific loadings, estimate the number of cooling tubes, no load current and leakage reactance of core type transformer.
- Develop the output equation of induction motor, discuss selection of specific loadings and magnetic circuits of induction motor, design stator and rotor circuits of a induction motor.
- Formulate the output equation of alternator, design the field windings of Synchronous machine, discuss short circuit ratio and its effects on performance of synchronous machines, design salient pole and non-salient pole alternators for given specifications.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - V HIGH VOLTAGE ENGINEERING CIE Marks Course Code 18EE56 40 Number of Lecture Hours/Week (L:T:P) 60 3:0:0 SEE Marks Exam Hours Credits 03 03 Credits - 03 **Course Learning Objectives:** To discuss conduction and breakdown in gases, liquid • dielectrics. To discuss breakdown in solid dielectrics. • To discuss generation of high voltages and currents and their measurement. • To discuss overvoltage phenomenon and insulation coordination in electric power systems. Module-1 Conduction and Breakdown in Gases: Gases as Insulating Media, Collision Process, Ionization Processes, Townsend's Current Growth Equation, Current Growth in the Presence of Secondary Processes, Townsend's Criterion for Breakdown, Experimental Determination of Coefficients α and γ , Breakdown in Electronegative Gases, Time Lags for Breakdown, Streamer Theory of Breakdown in Gases, Paschen's Law, Breakdown in Non-Uniform Fields and Corona Discharges. Conduction and Breakdown in Liquid Dielectrics: Liquids as Insulators, Pure Liquids and Commercial Liquids, Conduction and Breakdown in Pure Liquids, Conduction and Breakdown in Commercial Liquids. Breakdown in Solid Dielectrics: Introduction, Intrinsic Breakdown, Electromechanical Breakdown, Thermal Breakdown. ■ Module-2 Generation of High Voltages and Currents: Generation of High Direct Current Voltages. Generation of High Alternating Voltages, Generation of Impulse Voltages, Generation of Impulse Currents, Tripping and Control of Impulse Generators. Module-3 Measurement of High Voltages and Currents: Measurement of High Direct Current Voltages, Measurement of High AC and Impulse Voltages, Measurement of High Currents - Direct, Alternating Impulse, Cathode Ray Oscillographs for Impulse Voltage and Current and Measurements. Module-4 Overvoltage Phenomenon and Insulation Coordination in Electric Power Systems: National Causes for Overvoltages - Lightning Phenomenon, Overvoltage due to Switching Surges, System Faults and Other Abnormal, Principles of Insulation Coordination on High Voltage and Extra High Voltage Power Systems.∎ Module-5 Non-Destructive Testing of Materials and Electrical Apparatus: Introduction, Measurement of Dielectric Constant and Loss Factor, Partial Discharge Measurements. High Voltage Testing of Electrical Apparatus: Testing of Insulators and Bushings, Testing of Isolators and Circuit Breakers, Testing of Cables, Testing of Transformers, Testing of Surge Arrestors, Radio Interference Measurements, Testing of HVDC Valves and Equipment. **Course Outcomes:** At the end of the course the student will be able to: Explain conduction and breakdown phenomenon in gases, liquid dielectrics and breakdown • phenomenon in solid dielectrics. Summarize generation of high voltages and currents •

- Outline measurement techniques for high voltages and currents.
- Summarize overvoltage phenomenon and insulation coordination in electric power systems.
- Explain non-destructive testing of materials and electric apparatus, high-voltage testing of electric apparatus

IV SEMESTER DETAILED SYLLABUS

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VI

| CONTROL SYSTEMS (Core Subject) | | | | |
|--------------------------------------|--------|------------|----|--|
| Course Code | 18EE61 | CIE Marks | 40 | |
| Number of Lecture Hours/Week (L:T:P) | 3:2:0 | SEE Marks | 60 | |
| Credits | 04 | Exam Hours | 03 | |

Course Learning Objectives:

- To define a control system
- To explain the necessity of feedback and types of feedback control systems.
- To introduce the concept of transfer function and its application the modeling of linear systems.
- To demonstrate mathematical modeling of control systems.
- To obtain transfer function of systems through block diagram manipulation and reduction
- To use Mason's gain formula for finding transfer function of a system
- To discuss transient and steady state time response of a simple control system.
- To discuss the stability of linear time invariant systems and Routh-Hurwitz criterion
- To investigate the trajectories of the roots of the characteristic equation when a system parameter is varied.
- To conduct the control system analysis in the frequency domain.
- To discuss stability analysis using Bode plots.
- To determine the controller or compensator configuration and parameter values relative to how it is

Module-1

Introduction to Control Systems: Introduction, classification of control systems.

Mathematical models of physical systems: Modelling of mechanical system elements, electrical systems, Analogous systems, Transfer function, Single input single output systems, Procedure for deriving transfer functions, servomotors, synchros, gear trains. ■

Module-2

Block Diagram: Block diagram of a closed loop system, procedure for drawing block diagram and block diagram reduction to find transfer function.

Signal Flow Graphs: Construction of signal flow graphs, basic properties of signal flow graph, signal flow graph algebra, construction of signal flow graph for control systems. ■

Module-3

Time Domain Analysis: Standard test signals, time response of first order systems, time response of second order systems, steady state errors and error constants, types of control systems.

Routh Stability Criterion: BIBO stability, Necessary conditions for stability, Routh stability criterion, difficulties in formulation of Routh table, application of Routh stability criterion to linear feedback systems, relative stability analysis.

Module-4

Root locus Technique: Introduction, root locus concepts, construction of root loci, rules for the construction of root locus.

Frequency Response Analysis: Co-relation between time and frequency response – 2nd order systems only.

Bode Plots: Basic factors G(iw)/H(jw), General procedure for constructing bode plots, computation of gain margin and phase margin. ■

Module-5

Nyquist plot: Principle of argument, Nyquist stability criterion, assessment of relative stability using Nyquist criterion.

Design of Control Systems: Introduction, Design with the PD Controller, Design with the PI Controller, Design with the PID Controller, Design with Phase-Lead Controller, Design with Phase - Lag Controller, Design with Lead-Lag Controller.

- Analyze and model electrical and mechanical system using analogous.
- Formulate transfer functions using block diagram and signal flow graphs.
- Analyze the stability of control system, ability to determine transient and steady state time response.
- Illustrate the performance of a given system in time and frequency domains, stability analysis using Root locus and Bode plots.
- Discuss stability analysis using Nyquist plots, Design controller and compensator for a given specification.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER - VI

| | SEMESTER | - VI | |
|--|---|---|---|
| POWER SYS | FEM ANALYS | IS – 1 (Core Subject) | |
| Course Code | 18EE62 | CIE Marks | 4 |
| Number of Lecture Hours/Week (L:T:P) | 3:2:0 | SEE Marks | 6 |
| Credits | 04 | Exam Hours | 0 |
| Course Learning Objectives: To introduce the per unit system an To explain the concept of one line of To explain the necessity and condution To explain analysis of three phase systems. | diagram and its i | mplementation in problems. rcuit analysis. | and simple power |
| To discuss selection of circuit brea To explain symmetrical components of voltages and current To explain the concept of sequence To explain the concept of sequence generator, transformers and transm To explain the analysis of synchronous machine. Discuss stability and types of stabil evaluation of stability of a simple stability of a singl | ents, their advants in un-balance impedance and e networks and s dission lines. ronous machine etrical componer chronous machi ity for a power s | d three phase circuits. its analysis in three phase unbal- sequence impedances of an unlo and simple power systems fo its. ne and derive the power ang | anced circuits. aded synchronous r different le equation for a |
| Module-1 Representation of Power System Cor Balanced Three Phase Networks, One-Lin System, Steady State Model of Synchro Power, Representation of Loads. | ne Diagram and | Impedance or Reactance Diagra | am, Per Unit (PU) |
| Module-2 | | | |
| Symmetrical Fault Analysis: Introduction Synchronous Machine(On No Load), Sho examples on power systems. Selection of Co Module-3 | ort Circuit of a l | Loaded Synchronous Machine, | |
| Symmetrical Components: Introduction Star-Delta Transformers, Sequence Im Sequence Network of Power System, S Sequence Impedances of Transmission L Construction of Sequence Networks of a I Module-4 | pedances of T Sequence Impec ines, Sequence I Power System. | ransmission Lines, Sequence lances and Networks of Sync impedances and Networks of Tr | Impedances and hronous Machine ransformers, |
| Unsymmetrical Fault Analysis: Introduc Faults, Single Line-To-Ground (LG) Faul Fault, Open Conductor Faults. | | | |

Fault, Open Conductor Faults.

Module-5

Power System Stability: Introduction, Dynamics of a Synchronous Machine, Review of Power Angle Equation, Simple Systems, Steady State Stability, Transient Stability, Equal Area Criterion, Factors Affecting Transient Stability, Multi machine stability studies, classical representation.

- Model the power system components & construct per unit impedance diagram of power system.
- Analyze three phase symmetrical faults on power system.
- Compute unbalanced phasors in terms of sequence components and vice versa, also develop sequence networks.
- Analyze various unsymmetrical faults on power system.
- Examine dynamics of synchronous machine and determine the power system stability.

| B. E. ELECTRICA Choice Based Credit Syste | | TRONICS ENGINER l Outcome Based Edu | |
|---|--|--|---|
| • | SEMESTE | | |
| DIGITAL SIG | NAL PROCE | CSSING (Core Subject | t) |
| Course Code | 18EE63 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P) | 3:2:0 | SEE Marks | 60 |
| Credits | 04 | Exam Hours | 03 |
| Course Learning Objectives: To define Discrete Fourier trans To evaluate DFT of various sign To explain different linear filter To explain the evaluation of DF To discuss impulse invariant to properties. To design infinite impulse responsibilinear transformation techniq To discuss direct, cascade, para To discuss window functions us To discuss frequency sampling To discuss direct, cascade and 1 Module-1 | hals using prop ring techniques T and inverse ransformation, onse Butterwo ues. onse Chebyshe ues. llel and ladder sed for the desi e of designing technique of de inear phase for | erties of DFT. DFT using fast and effi- bilinear transformatio rth digital filters using t v digital filters using in methods of realizing a gn of FIR filters. FIR filter. esigning FIR filter. m of realizing a digital | n techniques and their impulse invariant and npulse invariant and digital IIR filter. FIR filter. |
| convolution – periodic convolution, use convolution – two finite duration seque methods. ■ Module-2 Fast Fourier Transforms Algorithm decomposition, number of computations, computational efficiency, decimation in finite duration. | ence, one finities: Introduction | te & one infinite dura on, decimation in ti of decomposition, num | me algorithm, first ber of multiplications, |
| Module-3 Design of IIR Digital Filters: Int transformations, All pole analog filt Butterworth filter by impulse invar transformations. ■ | roduction, im ers- Butterwo | pulse invariant tran orth & Chebyshev | sformation, bilinear filters, design of digita |
| Module-4 | | | |
| Design of IIR Digital Filters (Continued invariant transformation and bilinear trans Realization of IIR digital systems: dir equal degree polynomial. ■ | formation, Fre ect form, casc | quency transformations ade form and parallel | s. form, Ladder structures for |
| Design of FIR Digital Filters: Introd Hamming, Hanning, Blackman window, FIR digital filters-frequency sampling tec Realization of FIR systems: direct form, | design of FIR hniques. cascade form, | digital filters by use of linear phase form. ■ | |
| Course Outcomes: At the end of the course Apply DFT and IDFT to perform output. Apply fast and efficient algorithms Design and realize infinite impulse invariant and bilinear tran Develop a digital IIR filter by direction | for computing response But sformation tech | g techniques on given g DFT and inverse DFT terworth and Chebysho nniques. | of a given sequence v digital filters using |
| linear phase methods of realization Design and realize FIR filters by u | | unction and fragueness | sampling mathed |

• Design and realize FIR filters by use of window function and frequency sampling method.

| B. E. ELECTI CHOICE BASED CREDIT SY | RICAL AND ELECTRONIC STEM (CBCS) AND OUTCO | | N (OBE) |
|--|---|----------------------------|------------------|
| | SEMESTER – VI | | |
| INTRODUCTION TO | D NUCLEAR POWER (PRO | FESSIONAL ELECTIVE) | |
| Course Code | 18EE641 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| To explain the fission process in nuclea | r materials and how the nucl | lear reactors work and the | basic components |

To explain the fission process in nuclear materials and how the nuclear reactors work and the basic components of nuclear reactors and their types.

• Explanation about cooling of reactors, features of coolant, different types of coolants used in the reactors and the losses of cooling.

• Discussion on loss of cooling accidents in different reactors.

• Discussion on postulated severe accidents in water cooled reactors and other reactors and cooling of reactor during removal and processing.

• Discussion on cooling and disposing the nuclear waste and prospect of fusion energy in the future.

Module-1

The Earth and Nuclear Power: Sources and Resources: Introduction, Earth's Internal Heat Generation, The Earth's Energy Flow, The Fission Process, Thermal Energy Resources.

How Reactors Work: Introduction, The Fission Process, Basic Components of a Nuclear Reactor, Thermal Reactors, Fast Reactors.

Module-2

Cooling Reactors: Introduction, General Features of a Reactor Coolant, Principles of Heat Transfer, Gaseous Coolants, Liquid Coolants, Boiling Coolants.

Loss of Cooling: Introduction, The Electric Kettle, Pressurized-Water Reactor, Boiling-Water Reactor, CANDU Reactor, Gas-Cooled Reactors, Sodium- Cooled Fast Reactor.

Module-3

Loss-of-Cooling Accidents: Introduction, Incidents in light Water-Cooled Reactors, Heavy Water- Moderated Reactors, Gas-Cooled Reactors, Liquid Metal-Cooled Fast Reactors.

Module-4

Postulated Severe Accidents Introduction: Introduction, Postulated Severe Accidents in Water- Cooled Reactors, Specific Phenomena relating to Severe Accidents, Severe Accidents in other Reactor Types, Fission Product Dispersion following Containment Failure.

Cooling during Fuel Removal and Processing: Introduction, Refuelling, Spent Fuel Storage and Transport, Reprocessing Plant.

Module-5

Cooling and Disposing of the Waste: Introduction, Classification of Waste Products, Fission Products and Their Biological Significance, Options for Nuclear Waste Disposal, Long-Term Storage and Disposal of Spent Nuclear Fuel, Storage and Disposal of Fission Products from Reprocessing Plants, Disposal of other Materials.

Fusion Energy -Prospect for the Future: Introduction, The Fusion Process, Confinement, Current Technical Position, Conclusions.

- Explain the fission process in nuclear materials, basic components of nuclear reactors, types of nuclear reactors and their working.
- List different types of coolants, their features, and cooling of reactors,
- Summarize loss of cooling accidents in different reactors.
- Discuss postulated severe accidents in reactors and cooling of reactor during removal of spentfuel.
- Discuss cooling and disposing the nuclear waste and prospect of fusion energy in the future.

| B. E. ELECT CHOICE BASED CREDIT SY | , , | | N (OBE) |
|--|---|--|--|
| FI FCTPICAL FNCI | SEMESTER – VI NEERING MATERIALS (PRO | OFFSSIONAL FLECTIVE |) |
| Course Code | 18EE642 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | 05 | Examinours | 05 |
| To impart the knowledge of cond applications. To impart the knowledge of supercor Module-1 Introduction to Electrical and Elect | nducting materials and their a | pplications | |
| and electronic materials, Scope of electronic materials, Scope of electrical energy gap, Products – working of material structure. Spintronics an materials. Conductors: Conductor materials, Facurrent, Thermoelectric effect, Seebect relation, Problems. Module-2 | ctrical and electronic material l and electronic materials, principle and materials, ad Spintronic materials, Fer actors affecting conductivity | als, Requirement of Engir Classification of solids of Types of engineering m rromagnetic semiconductor, Thermal conductivity, I | heering materials, on the basis of laterials, Levels ors, Left handed Heating effect of |
| Conductive Materials and Applicat | | | |
| materials, Fusible materials, Filamen conductors, cables, wires, solder, sheat Dielectrics: Introduction to dielectr constant, Dielectric strength and Di of different polarization process, of polarization under impulse and fre Complex dielectric constant. | hing and sealing. ic materials, classificatio ielectric loss. Polarization, Factors affecting polarize | n of dielectric mater Mechanisms of polariza ation, Spontaneous polari | ials, Dielectric tion, Comparison zation, Behavior |
| Module-3 | | | |
| rubber. Paper. Choice of solid insulati – Requirements, Transformer oil, Bu Materials – Air, Nitrogen, Vacuum. Magnetic Materials: Origin of perri- relative permeability and magnetic Paramagnetism, Ferromagnetism, Ferrimagnetism and ferrites – properti- magnetic materials. Magnetization cur current loss. | eric materials – Bakelit ing material for different app ubble theory, Aging of mi- nanent magnetic dipole, M susceptibility. Classification Antiferromagnetic an ies and applications, Soft and | e, Polyethylene. Natura plications, Liquid insulatin ineral insulating oils. Ga Magnetic terminology, R on of magnetic materia d the correspondi d hard ferrites. Curie temp | al and synthetic g materials aseous insulating celation between ls, Diamagnetic, ng materials. berature, Laws of |
| Module-4 | | | |
| Magnetic Materials (continued):Type magnetic materials, Commercial grade Superconductive Materials: Com- superconductivity, Properties of superco- temperature, Effects of Isotopic mass coherence length. Ideal and Hard sup Type I superconductors, GLAG theory Applications of high temperature supe | soft and hard magnetic mater cept of superconductors, conductors, Types of supercon- ss on critical temperature, perconductors, Mechanism of for Type I superconductors, | rials. Meaning of phen nductors, Critical magnetic Silsbee rule, Depth of f super conduction, Lon BCS theory, Applications | nomenon of field and critical penetration and don's theory for and limitations. |

Module-5

Plastics: Introduction, Thermoplastics, Rubbers, Thermosets, DC and AC properties, Mechanical properties and processing of plastic.

Materials for Opto – Electronic Devices: Introduction, Optical phenomena, Reflection, Refraction, Transmittivity, Scattering, Optical absorption, Optical properties of non-metals, Optical properties of metals, Optical properties of semiconductors, Optical properties of insulators. Luminescence, Opto – Electronic devices, Photoconductivity, Photoconductive cell.

Course Outcomes: At the end of the course the student will be able to:

• Discuss electrical and electronics materials, their importance, classification and operational requirement

• Discuss conducting, dielectric, insulating and magnetic materials used in engineering, their properties and classification.

• Explain the phenomenon superconductivity, super conducting materials and their application in engineering.

• Explain the plastic and its properties and applications.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER – VI COMPUTER AIDED ELECTRICAL DRAWING (PROFESSIONAL ELECTIVE) Course Code 18EE643 CIE Marks 40 Teaching Hours/Week (L:T:P) (3:0:0)SEE Marks 60 03 Credits 03 Exam Hours **Course Learning Objectives:** • To discuss the terminology of DC and AC armature windings. • To discuss design and procedure to draw armature winding diagrams for DC and AC machines. • To discuss the substation equipment, their location in a substation and development of a layout for substation. • To discuss different sectional views of transformers, DC machine, its parts and alternator and itsparts. • To explain development of sectional views of Transformers, DC machine and alternators using the design data, sketches. Suitable CAD software can be used for drawings PART - A **Module-1** Winding Diagrams: (a) Developed Winding Diagrams of D.C. Machines: Simplex Double Layer Lap and Wave Windings. (b) Developed Winding Diagrams of A.C. Machines: (c)Integral and Fractional Slot Double Layer Three Phase Lap and Wave Windings. (d) Single Layer Windings – Un-Bifurcated 2 and 3 Tier Windings, Mush Windings, Bifurcated 3 Tier Windings. Module-2 Single Line Diagrams: Single Line Diagrams of Generating Stations and Substations Covering Incoming Circuits, Outgoing Circuits, Busbar Arrangements (Single, Sectionalised Single, Main and Transfer, Double Bus Double Breaker, Sectionalised Double Bus, One and a Half Circuit Breaker Arrangement, Ring Main), Power Transformers, Circuit Breakers, Isolators, Earthing Switches, InstrumentTransformers, Surge or Lightning Arresters, Communication Devices (Power-Line Carrier) and Line Trap. Module-3 Electrical Machine Assembly Drawings Using Design Data, Sketches or Both: Transformers - Sectional Views Of Single And Three Phase Core And Shell Type Transformers. Module-4 Electrical Machine Assembly Drawings Using Design Data, Sketches or Both: D.C. Machine - Sectional Views of Yoke with Poles, Armature and Commutator dealt separately. Module-5 Electrical Machine Assembly Drawings Using Design Data, Sketches or Both: Alternator – Sectional Views of Stator and Rotor dealt separately. **Course Outcomes:** At the end of the course the student will be able to: • Develop armature winding diagram for DC and AC machines

- Develop a Single Line Diagram of Generating Stations and substation using the standard symbols.
- Construct sectional views of core and shell types transformers using the design data
- Construct sectional views of assembled DC and AC machine and their parts using the design data or the sketches

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER - VI EMBEDDED SYSTEMS (PROFESSIONAL ELECTIVE) Course Code 18EE644 **CIE Marks** 40 Teaching Hours/Week (L:T:P) (3:0:0)SEE Marks 60 Credits 03 Exam Hours 03 **Course Learning Objectives:** • To understand the concepts of Embedded system design such as ROM variants, RAM, SOC • To learn the technological aspects of Embedded system such as signal conditioning, Sample & Hold. • To understand the design trade-offs. • To study about the software aspects of Embedded system. Module-1 Concept of Embedded System Design: Components, classification, skills required. Embedded Micro controller cores: Architecture of 6808 and 6811. Embedded Memories ROM variants, RAM. [Textbook -3 and Reference book -3] Module-2 Technological Aspects of Embedded System: Applications of embedded system: Examples of Embedded systems SOC for bar code scanner. Interfacing between analog and digital blocks, Signal conditioning, ADC digital signal processing, DAC & interfacing. Sample & hold, multiplexer interface Internal ADC interfacing (excluding 6805 & 6812). [Textbook -1] Module-3 Design Trade Offs Due to Process Incompatibility, Thermal Considerations: Data Acquisition System and Signal conditioning using DSP. Issues in embedded system design. Design challenge, design technology, trade-offs. Thermal considerations. [Reference book -1 and Internet Sources] Module-4 Software aspects of Embedded Systems: Real time programming Languages, operating systems. Programming concepts and embedded programming in C. Round Robin, Round Robin with interrupts, function queue-scheduling architecture. [Textbook -3 and Reference book -3] Module-5 Subsystem interfacing: With external systems user interfacing, Serial I/O devices, Parallel port interfaces: Input switches, Key boards and Memory interfacing. [Textbook -1] **Course Outcomes:** At the end of the course the student will be able to: • Identify the Embedded system components. • Apply technological aspects to various interfacing with devices.

- Elaborate various design trade-offs.
- Apply software aspects and programming concepts to the design of Embedded System.
- Explain how to interface subsystems with external systems.

| OBJECT ORIENTED PR | SEMESTER – VI OGRAMMING USING C++ | PROFESSIONAL ELECT | IVE) |
|--|---|---|---|
| Course Code | 18EE645 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| Define Encapsulation, Inheritance an | · · | | |
| • Solve the problem with object oriente | ed approach. | | |
| • Analyze the problem statement and b | uild object oriented system i | nodel. | |
| Describe the characters and behavior | of the objects that comprise | a system. | |
| • Explain function overloading, operate | or overloading and virtual fu | nctions. | |
| · Discuss the advantages of object orie | nted programming over proc | edure oriented programming | ng. |
| Module-1 | | | - |
| What is C++?, Applications and structure expressions, operator overloading and compared and comp | | | |
| | | | |
| | | | |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem | ory allocation to objects, arr | ay of objects, members, po | |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic | ory allocation to objects, arr | ay of objects, members, po | |
| Functions, Classes and Objects: Functions, Inline function, function ov- with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 | ory allocation to objects, arr cs from Chapter 4 and 5 of to | ay of objects, members, po extbook). | inters to members |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Operation | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Constru- | ay of objects, members, po extbook). ctors, Multiple constructors | inters to members |
| Functions, Classes and Objects: Functions, Inline function, function ov- with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper- constructor, Dynamic constructor, Des | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator | ay of objects, members, po extbook). extors, Multiple constructor overloading, Overloading | inters to members s in a class, Copy Unary and binary |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper constructor, Dynamic constructor, Des operators, Manipulation of strings using | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator | ay of objects, members, po extbook). extors, Multiple constructor overloading, Overloading | inters to members s in a class, Copy Unary and binary |
| Functions, Classes and Objects: Functions, Inline function, function ov- with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper- constructor, Dynamic constructor, Des operators, Manipulation of strings using Module-4 | ator Overloading: Construct tructors, Defining operator g operators. (Selected topics | ay of objects, members, po extbook). extors, Multiple constructor overloading, Overloading | inters to members s in a class, Copy Unary and binary |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper constructor, Dynamic constructor, Des operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: | ay of objects, members, po extbook). etors, Multiple constructor overloading, Overloading from Chapter 6 and 7 of to | inters to members s in a class, Copy Unary and binary extbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Operators, Destructor, Destructor, Destructor, Destructor, Destructor, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, metabolication of strings (Selected Topic) Module-4 (Selected Topic) Derived Classes, Single, multilevel, metabolication (Selected Topic) | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers | ay of objects, members, po extbook). etors, Multiple constructor overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla | inters to members s in a class, Copy Unary and binary extbook). |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper constructor, Dynamic constructor, Des operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, m pointer, Virtual and pure virtual function | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers | ay of objects, members, po extbook). etors, Multiple constructor overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla | inters to members s in a class, Copy Unary and binary extbook). |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Opera constructor, Dynamic constructor, Des operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, m pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: | ory allocation to objects, arr cs from Chapter 4 and 5 of to ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Ch | ay of objects, members, poextbook). extbook). extors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). | inters to members s in a class, Copy Unary and binary extbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, m pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, forma for file stream operations, opening and operators | ator Overloading: Construct tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Char ttted and unformatted I/O op closing a file, EOF (Selected | ay of objects, members, po extbook). etors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes |
| Functions, Classes and Objects: Functions, Inline function, function ov with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, ma pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formatorial for file stream operations, opening and operators. | ator Overloading: Construct tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Char ttted and unformatted I/O op closing a file, EOF (Selected | ay of objects, members, po extbook). etors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem- and member functions. (Selected Topic Module-3 Constructors, Destructors and Opera- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, ma pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formation for file stream operations, opening and con- Course Outcomes: At the end of the con- • Explain the basics of Object Oriented | ator Overloading: Construct ator Overloading: Construct g operators. (Selected topics ons, Polymorphism: multiple inheritance, Pointers ons (Selected topics from Char etted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem- and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, me pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formation for file stream operations, opening and operations, opening and operations Module-1 Course Outcomes: At the end of the con- Magnetic Stream operations of the con- Magnetic Stream operation operation of the con- Magnetic Stream operation opera | ator Overloading: Construct ator Overloading: Construct g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Char etted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construct | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem- and member functions. (Selected Topic Module-3 Constructors, Destructors and Opera- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, m- pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, forma- for file stream operations, opening and of Course Outcomes: At the end of the cu- • Explain the basics of Object Oriented • Apply the object initialization and de • Apply the concept of polymorphism | ator Overloading: Construct ator Overloading: Construct g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Char etted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construct | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, me pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formation for file stream operations, opening and operations, opening and operations, opening and de • Explain the basics of Object Oriented • Apply the object initialization and de • Apply the concept of polymorphism overloading methods and operators. | ator Overloading: Construct tructors, Defining operator g operators. (Selected topics ons, Polymorphism: aultiple inheritance, Pointers ons (Selected topics from Char atted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construct to implement compile time | ay of objects, members, po extbook). etors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. polymorphism in programs | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem- and member functions. (Selected Topic Module-3 Constructors, Destructors and Opera- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, ma- pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formation for file stream operations, opening and of Course Outcomes: At the end of the co- • Explain the basics of Object Oriented • Apply the concept of polymorphism overloading methods and operators. • Utilize the concept of inheritance to re- | ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: multiple inheritance, Pointers ons (Selected topics from Char etted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construc- to implement compile time preduce the length of code and | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. polymorphism in programs I evaluate the usefulness. | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |
| Functions, Classes and Objects: Functions, Inline function, function over with a class, arrays within a class, mem and member functions. (Selected Topic Module-3 Constructors, Destructors and Operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, me pointer, Virtual and pure virtual function Module-5 Streams and Working with Files: C++ streams and stream classes, formator for file stream operations, opening and of Course Outcomes: At the end of the con- entities of Object Oriented Apply the object initialization and de Apply the concept of polymorphism overloading methods and operators. | ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: multiple inheritance, Pointers ons (Selected topics from Char etted and unformatted I/O op closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construc- to implement compile time preduce the length of code and | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. polymorphism in programs I evaluate the usefulness. | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |
| and member functions. (Selected Topic Module-3 Constructors, Destructors and Oper- constructor, Dynamic constructor, Des- operators, Manipulation of strings using Module-4 Inheritance, Pointers, Virtual Function Derived Classes, Single, multilevel, ma pointer, Virtual and pure virtual function Module-5 | ator Overloading: Construc- tructors, Defining operator g operators. (Selected topics ons, Polymorphism: ultiple inheritance, Pointers ons (Selected topics from Ch- etted and unformatted I/O op- closing a file, EOF (Selected ourse the student will be able d Programming concepts. stroy concept using construc- to implement compile time reduce the length of code and orphism by using virtual func- | ay of objects, members, po extbook). ctors, Multiple constructors overloading, Overloading from Chapter 6 and 7 of to to objects and derived cla apter 8 and 9 of textbook). erations, Output with man topics from Chapters 10 an e to: tors and destructors. polymorphism in programs I evaluate the usefulness. | inters to members s in a class, Copy Unary and binary extbook). asses, this ipulators, Classes d 11 of textbook). |

| B. E. ELECT CHOICE BASED CREDIT SY | RICAL AND ELECTRONIC (STEM (CBCS) AND OUTCO | | DN (OBE) |
|---|--|--|---|
| | SEMESTER – VI LE TECHNOLOGIES (PROI | | |
| Course Code | 18EE646 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: To understand working of Electric Ve Ability to analyze different power con Ability to develop the electric propuls Ability to design converters for batter | nverter topology used for ele sion unit and its control for a | pplication of electric veh | icles. |
| Module-1 Electric and Hybrid Electric Vehicles Vehicles, Traction motor characte | : Configuration of Electric V ristics, Tractive effort | Vehicles, Performance of and Transmission req | |
| Vehicle performance, Tractive effo Electric Drive Trains, Architecture of H Parallel hybrid electric drive trains. | rt in normal driving, En | ergy consumption Conc | ept of Hybrid |
| Module-2 | | | |
| Energy storage for EV and HEV: End Modelling of Battery, Fuel Cell basic its operation, Modelling of PEMFC, Su Module-3 Electric Propulsion: EV consideration Magnet Motor Drives, Switch Reluctance Module-4 | principle and operation, Typercapacitors. | ypes of Fuel Cells, | PEMFC and |
| Design of Electric and Hybrid Elec patterns, control strategies, Sizing of engine/generator, design of PPS Parallel drive train, design of engine power capa storage design. Module-5 | major components, power Hybrid Electric Drive Train | rating of traction moto Design: Control strategie | r, power rating of es of parallel hybrid |
| Power Electronic Converter for Batt charging from grid, The Z-converter, Is battery charging, High-frequency tran | olated bidirectional DC-DC | converter, Design of Z- c | converter for |
| Course Outcomes: At the end of the co • Explain the working of electric vehicl • Analyze different power converter top | les and recent trends. | cle application. | |

| Course Code Teaching Hours/Week (L:T:P) Credits Course Learning Objectives: • Explain the use of gauges and transradiations • Explain the transducers used for temp • Explain the sensors and transducers used for temp • Explain the sensors and transducers used for temp • Explain the sensors and transducers used for temp | SEMESTER – VI ANSDUCERS (PROFES 18EE647 (3:0:0) 03 sducers to measure press perature sensing, and for t | SIONAL ELECTIVE) CIE Marks SEE Marks Exam Hours ure, direction, distance and he measurement of sound. | 40 60 03 |
|---|---|--|-------------------|
| Course Code Teaching Hours/Week (L:T:P) Credits Course Learning Objectives: • Explain the use of gauges and transradiations • Explain the transducers used for temp • Explain the sensors and transducers used for temp • Explain the sensors and transducers used for temp • Explain the sensors and transducers used for temp | ANSDUCERS (PROFES 18EE647 (3:0:0) 03 sducers to measure press perature sensing, and for t | CIE Marks SEE Marks Exam Hours ure, direction, distance and he measurement of sound. | 60 03 |
| Teaching Hours/Week (L:T:P) Credits Course Learning Objectives: • Explain the use of gauges and transradiations • Explain the transducers used for temp • Explain the sensors and transducers up quantities. | (3:0:0) 03 sducers to measure press perature sensing, and for t | SEE Marks Exam Hours ure, direction, distance and he measurement of sound. | 60 03 |
| Credits Course Learning Objectives: Explain the use of gauges and transradiations Explain the transducers used for temp Explain the sensors and transducers uquantities. | 03 oducers to measure press perature sensing, and for t | Exam Hours ure, direction, distance and he measurement of sound. | 03 |
| Course Learning Objectives: Explain the use of gauges and transradiations Explain the transducers used for temp Explain the sensors and transducers uquantities. | sducers to measure press | ure, direction, distance and he measurement of sound. | |
| Explain the use of gauges and transradiations Explain the transducers used for temp Explain the sensors and transducers up quantities. | perature sensing, and for t | he measurement of sound. | electromagnetic |
| radiations Explain the transducers used for temp Explain the sensors and transducers u quantities. | perature sensing, and for t | he measurement of sound. | electromagnetic |
| quantities. | | l of mass, volume and envir | onmental |
| | | | |
| Module-1 | | | |
| Strain and Pressure: Mechanical strain, | Interferometry, Fibre opt | tic methods, pressure gauge | s, low gas |
| pressures, Ionization gauges, Transducer u | | | - |
| Position, direction, distance, and motion | on: Position, Direction, | Distance measurement, Di | stance travelled, |
| Accelerometer systems, Rotation. | | | |
| Module-2 | | | |
| transducers, Solid-state transducers, Liqu waves. Module-3 | | | |
| Temperature sensors and thermal tran expansion, Thermocouples, Metal – resist detectors, Thermal transducers, Thermal to | ance sensors, Thermistor | | |
| Module-4 | | | |
| Sound, infrasound and ultrasound: H | Principles Audio electr | ical sensors and transduce | ers Electrical to |
| audio transducers. | meiples, Audio electi | ical sensors and transduce | is, Electrical to |
| Module-5 | | | |
| Solids, liquids and gases: Mass and volum | ne. Electronic sensors. Pr | oximity detectors. Liquid le | vels. Liquid flow |
| sensors, Timing, Gases, Viscosity. | -,, | ., <u>1</u> | 1 |
| Environmental Sensors: Environmental of | quantities, Time, Moisture | e, Acidity/alkalinity, Wind c | hill, Radioactive |
| count rate, Surveying and security, Anim | | | |
| Building acoustics. | · 1 | | , |
| Course Outcomes: At the end of the cour | se the student will be able | e to: | |
| • Use gauges and transducers to measure | | | |
| • Discuss the use of light transducers radiations. | - | | electromagnetic |
| Explain the working of different temp | perature sensing devices | | |
| Discuss the principles and application of sound. | - | ors and transducers used for | the measurement |
| Discuss the use of sensors for the mea | asurement of mass, volum | e and environmental quanti | ties. |

IV SEMESTER DETAILED SYLLABUS

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII

| POWER SYSTEM ANALYSIS – 2(Core Course) | | | | | | |
|--|--------------------------|-----------|----|--|--|--|
| Course Code | 18EE71 | CIE Marks | 40 | | | |
| Number of Lecture Hours/Week | 2:2:0 | SEE Marks | 60 | | | |
| Credits | Credits 03 Exam Hours 03 | | | | | |

Course Learning Objectives:

• To explain formulation of network models and bus admittance matrix for solving load flow problems.

- To discuss optimal operation of generators on a bus bar and optimum generation scheduling.
- To explain symmetrical fault analysis and algorithm for short circuit studies.
- To explain formulation of bus impedance matrix for the use in short circuit studies on power systems.
- To explain numerical solution of swing equation for multi-machine stability

Module-1

Network Topology: Introduction and basic definitions of Elementary graph theory Tree, cut-set, lomp analysis. Formation of Incidence Matrices. Primitive network- Impedance form and admittance form, Formation of Y Bus by Singular Transformation. Y_{bus} by Inspection Method. Illustrative examples. T1,2

Module-2

Load Flow Studies: Introduction, Classification of buses. Power flow equation, Operating Constraints, Data for Load flow, Gauss Seidal iterative method. Illustrative examples. T1, R1

Module-3

Load Flow Studies(continued) Newton-Raphson method derivation in Polar form, Fast decoupled load flow method, Flow charts of LFS methods. Comparison of Load Flow Methods. Illustrative examples. T1, R1

Module-4

Economic Operation of Power System: Introduction and Performance curves Economic generation scheduling neglecting losses and generator limits Economic generation scheduling including generator limits and neglecting losses Economic dispatch including transmission losses Derivation of transmission loss formula. Illustrative examples.T1

Unit Commitment: Introduction, Constraints and unit commitment solution by prior list method and dynamic forward DP approach (Flow chart and Algorithm only). T3

Module-5

Symmetrical Fault Analysis: Z Bus Formulation by Step by step building algorithm without mutual coupling between the elements by addition of link and addition of branch. Illustrative examples.Z bus Algorithm for Short Circuit Studies excluding numerical.T1

Power System Stability: Numerical Solution of Swing Equation by Point by Point method and Runge Kutta Method. Illustrative examples. T1

- Formulate network matrices and models for solving load flow problems.
- Perform steady state power flow analysis of power systems using numerical iterative techniques.
- Solve issues of economic load dispatch and unit commitment problems.
- Analyze short circuit faults in power system networks using bus impedance matrix.
- Apply Point by Point method and Runge Kutta Method to solve Swing Equation.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII

| - | SEMESTE | R – VII | |
|--|---|---|--|
| POWER SYS | STEM PROTI | ECTION (Core Subject) | |
| Course Code | 18EE72 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| To discuss performance of protect terminology. To explain relay construction and To explain Over current protection protective schemes. To discuss types of electromagnet swings, line length and source im To discuss pilot protection; wire p To discuss construction, operating relays for differential protection. To discuss protection of generator Protection. To explain the principle of circuit | operating princ on using electro ic and static dis pedance on per pilot relaying an g principles and rs, motors, Tran | ciples. magnetic and static relays stance relays, effect of arc formance of distance relay d carrier pilot relaying. I performance of various d nsformer and Bus Zone | and Over current resistance, power s. ifferential |
| To explain the principle of circuit breakers. To describe the construction and or give the definitions of different te To discuss protection Against Ov | operating princ rminologies re | iple of different types of ful lated to a fuse. | uses and to |
| Introduction to Power System Prote Faults, Types of Fault, Effects of Fa Protection, Essential Qualities of Pro- Protective Relays, Automatic Reclosing Protection. Relay Construction and Operating Relays – Merits and Demerits of Electromechanical Relays and Numerica Overcurrent Protection: Introduction, | ults, Fault Sta otection, Perfor g, Current Tran Principles: In Static Relays al Relays. | tistics, Zones of Protecti rmance of Protective Re- nsformers for protection, troduction, Electromecha , Numerical Relays, Co | ion, Primary and Backup elaying, Classification of Voltage Transformers for nical Relays, Static omparison between |
| Module-2 | | | |
| Overcurrent Protection (continued Directional Relay, Protection of Paralle Protection, Combined Earth Fault and Directional Earth Fault Relay, Static Ove Distance Protection: Introduction, Impedance Relay, Effect of Arc Res Distance Relays. Effect of Power Surg Line Length and Source Impedance on P Module-3 | I Feeders, Pro Phase Fault P ercurrent Relay Impedance F sistance on the ges(Power Switt | tection of Ring Mains, Ea rotective Scheme, Phase vs, Numerical Overcurrent telay, Reactance Relay he Performance of Dis ngs) on Performance of I | Fault Protective Scheme, Relays. , Mho Relay, Angle stance Relays, Reach o |
| Pilot Relaying Schemes: Introduction, V Differential Protection: Introduction, V Biased Differential Relay, Differential Differential Protection. Rotating Machines Protection: Introdu Transformer and Buszone Protection | Differential Re l Protection on action, Protection | elays, Simple Differential f 3 Phase Circuits, Bala on of Generators. | Protection, Percentage or anced (Opposed) Voltage |
| Laskage Protection | | | |

Leakage Protection.

Module-4

Circuit Breakers: Introduction, Fault Clearing Time of a Circuit Breaker, Arc Voltage, Arc Interruption, Restriking Voltage and Recovery Voltage, Current Chopping, Interruption of Capacitive Current, Classification of Circuit Breakers, Air – Break Circuit Breakers, Oil Circuit Breakers, Air – Blast Circuit Breakers, SF6 Circuit Breakers, Vacuum Circuit Breakers, High Voltage Direct Current Circuit Breakers, Rating of Circuit Breakers, Testing of Circuit Breakers.

Module-5

Fuses: Introductions, Definitions, Fuse Characteristics, Types of Fuses, Applications of HRC Fuses, Selection of Fuses, Discrimination.

Protection against Overvoltages: Causes of Overvoltages, Lightning phenomena, Wave Shape of Voltage due to Lightning, Over Voltage due to Lightning, Klydonograph and Magnetic Link, Protection of Transmission Lines against Direct Lightning Strokes, Protection of Stations and Sub – Stations from Direct Strokes, Protection against Travelling Waves, Insulation Coordination, Basic Impulse Insulation Level (BIL).

Modern Trends in Power System Protection: Introduction, gas insulated substation/switchgear (GIS).

- Discuss performance of protective relays, components of protection scheme and relay terminology over current protection.
- Explain the working of distance relays and the effects of arc resistance, power swings, line length and source impedance on performance of distance relays.
- Discuss pilot protection, construction, operating principles and performance of differential relays and discuss protection of generators, motors, transformer and Bus Zone Protection.
- Explain the construction and operation of different types of circuit breakers.
- Outline features of fuse, causes of overvoltages and its protection, also modern trends in Power System Protection.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VII

| · | SEMESTEI | R – VII | |
|--|-----------------------------------|---|---|
| | | GY (Professional Elective) | |
| Course Code | 18EE731 | CIE Marks | 40 |
| Number of Lecture Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| To discuss the importance of energy use To discuss the increasing role or | | | - |
| audit, energy efficiency, energy in | tensity. | | |
| • To discuss energy consumption s energy conservation efforts in Inc | lia. | | |
| • To explain the concept of energy devices. | - | | |
| • To discuss the characteristics and of solar radiation and analysis of c | ollected solar ra | adiation data. | • |
| • To explain availability of solar rad of collector with respect to horizo | ntal surface. | - | |
| • To describe the process of harne collectors. | essing solar ene | rgy in the form of heat and | working of solar |
| To discuss applications of solar er | nergy including | heating and cooling. | |
| • To discuss the operation of solar solar cell | cell and the env | vironmental effects on electric | al characteristics of |
| • To discuss sizing and design of ty | pical solar PV s | systems and their applications. | |
| • To discuss basic Principles of Wi in the wind. | nd Energy Con | version and to compute the po | ower available |
| To discuss forces on the Blades energy estimation and site selecti To discuss classification of WEC of Wind Machines (Wind Energy | on. Systems, its a | | |
| To evaluate the performance of W | | Generating Systems. ■ | |
| Module-1 | | | |
| Fundamentals of Energy Science a Development, Classification of Energy S features of Non-conventional Energy S | ources, Importa Sources, World | ance of Non -conventional End Energy Status, Energy Stat | ergy Sources, Salient us in India. Energ |
| Conservation and Efficiency: Introdu | - | | |
| Energy Conservation, Global Efforts, Ac | | <i>c c</i> | nservation/Efficienc |
| Scenario in India, Energy Audit, Energy | | | |
| Energy Storage: Introduction, Necessi Solar Energy-Basic Concepts: Introd | | | |
| Radiation Spectrum, Extraterrestrial an Radiation, Depletion of Solar Radiation. | nd Terrestrial | | |
| Module-2 | | | |
| Solar Energy-Basic Concepts (contin Data, Solar Time, Solar Radiation C Horizontal Surface, Empirical Equatio Surface, Solar Radiation on Inclined Pla | beometry, Sola ns for Estimat | r Day Length, Extraterrest | rial Radiation on |

Solar Thermal Systems: Introduction, Solar Collectors, Solar Water Heater, Solar Passive Space Heating and Cooling Systems, Solar Industrial Heating Systems, Solar Refrigeration and Air Conditioning Systems, Solar Cookers. ■

Module-3

Solar Photovoltaic Systems: Introduction, Solar Cell Fundamentals, Solar Cell Characteristics, Solar Cell Classification, Solar Cell Technologies, Solar Cell, Module, and Array Construction, Maximizing the Solar PV Output and Load Matching. Maximum Power Point Tracker. Balance of System Components, Solar PV Systems, Solar PV Applications.

Module-4

Wind Energy: Introduction, Basic Principles of Wind Energy Conversion, History of Wind Energy, Wind Energy Scenario – World and India. The Nature of the Wind, The Power in the Wind, Forces on the Blades, Wind Energy Conversion, Wind Data and Energy Estimation, Site Selection Considerations **Wind energy systems:** Environment and Economics Environmental benefits and problems of wind energy, Economics of wind energy, Factors influence the cost of energy generation, machine parameters, Life cycle cost analysis

Module-5

Basic Components of a Wind Energy Conversion(WEC) System: Classification of WEC systems, Advantages and Disadvantages of WECS, Types of Wind Machines (Wind Energy Collectors), Analysis of Aerodynamic Forces Acting on the Blade, Performance of Wind- machines, Generating Systems, Energy Storage, Applications of Wind Energy, Environmental Aspects.

Course Outcomes:

At the end of the course the student will be able to:

- Discuss the importance of the role of renewable energy, the concept of energy storage and the principles of energy storage devices.
- Discuss the concept of solar radiation data and solar PV system fabrication, operation of solar cell, sizing and design of PV system.
- Describe the process of harnessing solar energy and its applications in heating and cooling.
- Explain basic Principles of Wind Energy Conversion, collection of wind data, energy estimation and site selection.
- Discuss the performance of Wind-machines, energy storage, applications of Wind Energy and environmental aspects.

| CHOICE BASED CREDIT SY | | | N (OBE) |
|---|--|--|---|
| MICRO- AND NANO-SCALE S | SEMESTER – VII SENSORS AND TRANSDUCI | ERS (PROFESSIONAL EI | LECTIVE) |
| Course Code | 18EE732 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: To explain measurement of preoperation. To explain structure, theory of o measurement, gas and smoke dete To explain sensors based on nanoinside the electronic components. To explain Optoelectronic and F highly sensitive seismic sensors. To explain the structure, operatio Chip" sensors used in multipurpor RF/Microwave, Integrated Sensor | peration of sensors based or ection. Detechnology for the measurer Photonic Sensors used in opt n of Biological Sensors, Cher use biological and chemical a | n nanotechnology for Mo ment of atmospheric mois tical microphones, finger mical Sensors, and the so nalysis devices and Elect | otion, acceleration sture and moistur print readers, and -called "Lab-on-a ric, Magnetic, and |
| Module-1 Pressure Sensors: Capacitive Pressur Sensors. | * | <u>^</u> | |
| Module-2 Motion and Acceleration Sensors: U Acceleration Microsensors. | Iltrahigh Sensitivity, Wide D | ynamic Range Sensors, | Other Motion and |
| Gas and Smoke Sensors: A CO Gas S | ensor Based on Nanotechnol | ogy, Smoke Detectors. | |
| Module-3 | | | |
| Moisture Sensors: Structure, Theory, Optoelectronic and Photonic Sensors Sensors. Module-4 | | • • | |
| Biological, Chemical, and "Lab on a Nano-Sensors. Electric, Magnetic, and RF/Mi Electromagnetic/RF Micro- and Nano- Module-5 | crowave Sensors: Magn | | emical Micro- and Other Importan |
| Integrated Sensor/Actuator Units an Purpose Small-Scale Devices. | d Special Purpose Sensors: | Aircraft Icing Detectors, | Other Special |
| Course Outcomes: At the end of the constraint of the differences between nanofabrication and the classical section of a selection of a selection of a selection of a selection. | en the sensor and transducer t sensor technologies | technology based on nano | technology and |

Make an informed selection of a sensor or transducer for a particular application;
Become knowledgeable about the technologies that are available commercially at the present time.

| B. E. ELECT CHOICE BASED CREDIT SY | RICAL AND ELECTRONIC YSTEM (CBCS) AND OUTCO SEMESTER – VII | | N (OBE) |
|---|--|--|---|
| INTEGRATION OF DIST | RIBUTION GENERATION (| PROFESSIONAL ELECT | TVE) |
| Course Code | 18EE733 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | l | |
| • To explain power generation by alter | nate energy source like wind | power and solar power. | |
| • To explain selection of size of units a | | | |
| Discuss the effects of integration of d | | • | |
| 0 | | • | |
| • To provide practical and useful inform | mation about grid integration | of distributed generation. | |
| Module-1 | | | |
| Distributed Generation: Introduction of wind speed, Solar Power: Status, production capacity, Combined Heat- of Large Hydro, Properties of small Hy Thermal Power Plant. | Properties, Space requirem and-Power: Status, Options | ents, Photovoltaic's, Seas for space Heating, Hydro | sonal variation in opower: Properties |
| Module-2 | | | |
| Distributed Generation on the Power S Quality, Voltage Quality and Design Increasing the Hosting Capacity. Ove Radial Distribution Networks, Active Redundancy and Meshed Operation, | of Distributed Generation erloading and Losses: Impace Power Flow Only, Active | , Hosting Capacity Appr ct of Distributed Generat e and Reactive Power F | roach for Events, ion, Overloading: 'low Overloading: |
| Module-3 | | | |
| Over loading and Losses (continu Building New Connections, Inter trip | | | |
| Power Electronics approach, Demand G | | | • |
| Voltage Magnitude Variations: Imp | | | |
| Voltage Control in Distribution Syste | | e | |
| Estimating hosting capacity without | | | - <u>-</u> - |
| Feeders: Basic Design Rules, Termin | | | n of Distribution |
| Low voltage feeders, Series and Sh | | erator Along a Medium | |
| Example for Two-stage Boosting, Gen | unt Compensation, A Nur | | n-Voltage Feeder, |
| Compensation: Transformer with One | - | nerical Approach to V | n-Voltage Feeder, oltage Variations: |
| | eral Expressions for Two-Sta | nerical Approach to Vo age Boosting Tap Changer | n-Voltage Feeder, oltage Variations: rs with Line- Drop |
| of Distribution Feeders: Need for Pr | eral Expressions for Two-Sta e Single Feeder, Adding a | nerical Approach to Vo age Boosting Tap Changer Generator. Probabilistic M | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design |
| - | eral Expressions for Two-Sta e Single Feeder, Adding a | nerical Approach to Vo age Boosting Tap Changer Generator. Probabilistic M | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. | eral Expressions for Two-Sta e Single Feeder, Adding a | nerical Approach to Vo age Boosting Tap Changer Generator. Probabilistic M | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach | nerical Approach to Ve age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo | eral Expressions for Two-Sta e Single Feeder, Adding a cobabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol owing Higher Overvoltage' | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (continued to the content of the co | eral Expressions for Two-Sta e Single Feeder, Adding a cobabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol owing Higher Overvoltage' | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. | eral Expressions for Two-State Single Feeder, Adding a cobabilistic Methods, The Statistical Approach alternative Methods for Volowing Higher Overvoltage' ators voltage variations, Di | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Increa tage Control Accurate M s Overvoltage Protectio stributed generation with | h-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage h voltage control, |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. Power Quality Disturbances: Imp | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol owing Higher Overvoltage' ators voltage variations, Di pact of Distributed Genera | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio stributed generation with | n-Voltage Feeder, oltage Variations: rs with Line- Drop Methods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. Power Quality Disturbances: Imp Fluctuations in Wind Power, Fast H | eral Expressions for Two-State single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol- owing Higher Overvoltage' ators voltage variations, Di- pact of Distributed Genera Fluctuations in Solar Powe | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan | h-Voltage Feeder, oltage Variations: rs with Line- Drop Iethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (cont Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. Power Quality Disturbances: Imp Fluctuations in Wind Power, Fast H Variations. Voltage Unbalance: Weak | eral Expressions for Two-State single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol- owing Higher Overvoltage' ators voltage variations, Di- pact of Distributed Genera Fluctuations in Solar Powe for Transmission System, St | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan | h-Voltage Feeder, oltage Variations: rs with Line- Drop Iethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (continued to the content of the co | eral Expressions for Two-State single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol- owing Higher Overvoltage' ators voltage variations, Di- pact of Distributed Genera Fluctuations in Solar Powe for Transmission System, St | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan | n-Voltage Feeder, oltage Variations: rs with Line- Drop Iethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (contr Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. Power Quality Disturbances: Imp Fluctuations in Wind Power, Fast H Variations. Voltage Unbalance: Weak Phase Generators, Stronger Distribution Module-5 | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol owing Higher Overvoltage' ators voltage variations, Di eact of Distributed Genera Fluctuations in Solar Powe for Transmission System, Sta n Grid Voltage Unbalance. | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre- tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan- ronger Distribution Syste | n-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short m, Large Single- |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (conti Capacity: New or Stronger Feeders, A Voltage Magnitude Variations, Allo Curtailment Compensating the gener Coordinated voltage control. Power Quality Disturbances: Imp Fluctuations in Wind Power, Fast I Variations. Voltage Unbalance: Weak Phase Generators, Stronger Distribution | eral Expressions for Two-Sta e Single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol- owing Higher Overvoltage' ators voltage variations, Di- pact of Distributed Genera Fluctuations in Solar Powe for Transmission System, Sta n Grid Voltage Unbalance. | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan ronger Distribution Syste onics: Wind Power: Indu | n-Voltage Feeder, oltage Variations: rs with Line- Drop Iethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short m, Large Single- uction Generators, |
| of Distribution Feeders: Need for Pr Production, Adding Wind Power. Module-4 Voltage Magnitude Variations (continued to the content of the co | eral Expressions for Two-State single Feeder, Adding a robabilistic Methods, The S inued):Statistical Approach Alternative Methods for Vol- owing Higher Overvoltage' ators voltage variations, Di- pact of Distributed Genera Fluctuations in Solar Powe ater Transmission System, State of Grid Voltage Unbalance. | nerical Approach to Va age Boosting Tap Changer Generator. Probabilistic M System Studied, Generati to Hosting Capacity, Incre- tage Control Accurate M s Overvoltage Protectio stributed generation with ation, Fast Voltage F r, Rapid Voltage Chan, ronger Distribution Syste onics: Wind Power: Indu erators, Measurement Ex Grid. High-Frequency Dis | h-Voltage Feeder, oltage Variations: rs with Line- Drop fethods for Design on with Constant easing the Hosting easurement of the on, Over Voltage n voltage control, fluctuations: Fast ges, Very Short m, Large Single- action Generators, cample, Harmonic stortion: Emission |

Synchronous Machines Balanced Dips and Unbalanced Dips, Induction generators and unbalanced dips. Increasing the Hosting Capacity: Strengthening the Grid, Emission Limits for Generator Units, Emission Limits for Other Customers, Higher Disturbance Levels, Passive Harmonic Filters, Power Electronics Converters, Reducing the Number of Dips, Broadband and High-Frequency Distortion.

Course Outcomes: At the end of the course the student will be able to:

• Explain energy generation by wind power and solar power.

• Discuss the variation in production capacity at different time scales, the size of individual units, and the flexibility in choosing locations with respect to wind and solar systems.

• Explain the performance of the system when distributed generation is integrated to the system.

• Discuss effects of the integration of DG: the increased risk of overload, increased losses, increased risk of overvoltages and increased levels of power quality disturbances.

• Discuss effects of the integration of DG: incorrect operation of the protection.

• Discuss the impact the integration of DG on power system stability and operation.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) **SEMESTER - VII** ADVANCED CONTROL SYSTEMS (PROFESSIONAL ELECTIVE) Course Code CIE Marks 40 18EE734 Teaching Hours/Week (L:T:P) (3:0:0)SEE Marks 60 Credits Exam Hours 03 03 **Course objectives:** To introduce state variable approach for linear time invariant systems in both the continuous and discrete time systems. To explain development of state models for linear continuous – time and discrete – time systems. • To explain application of vector and matrix algebra to find the solution of state equations for • linear continuous - time and discrete - time systems. To define controllability and observability of a system and testing techniques for controllability and • observability of a given system. To explain design techniques of pole assignment and state observer using state feedback. To explain about inherent and intentional nonlinearities that can occur in control system and • developing the describing function for the nonlinearities. To explain stability analysis of nonlinear systems using describing function analysis. To explain the analysis of nonlinear systems using Lyapunov function and design of Lyapunov function for stable systems. Module-1 State Variable Analysis and Design: Introduction, Concept of State, State Variables and State Model, State Models for Linear Continuous–Time Systems, State Variables and Linear Discrete–Time Systems. Module-2 State Variable Analysis and Design (continued): Diagonalization, Solution of State Equations, Concepts of Controllability and Observability. Module-3 Pole Placement Design and State Observers: Introduction, Stability Improvements by State Feedback, Necessary and Sufficient Conditions for Arbitrary Pole Placement, State Regulator Design, Design of State Observer, Compensator Design by the Separation Principle. Module-4 Non-linear systems Analysis: Introduction, Common Nonlinear System Behaviours, Common Nonlinearities in Control Systems, Fundamentals, Describing Functions of Common Nonlinearities, Stability Analysis by Describing Function Method, Concept of Phase Plane Analysis, Construction of Phase Portraits, System Analysis on the Phase Plane. Module-5 Non-linear systems Analysis (continued): Simple Variable Structure Systems, Lyapunov Stability Definitions, Lyapunov Stability Theorems, Lyapunov Functions for Nonlinear Systems. **Course Outcomes:** At the end of the course the student will be able to: • Discuss state variable approach for linear time invariant systems in both the continuous and discrete time systems. • Develop of state models for linear continuous-time and discrete-time systems.

- Apply vector and matrix algebra to find the solution of state equations for linear continuous– time and discrete–time systems.
- Define controllability and observability of a system and test for controllability and observability of a given system.
- Design pole assignment and state observer using state feedback.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER – VII

| REACTIVE POWER CONTROL IN ELECTRIC POWER SYSTEMS (PROFESSIONAL ELECTIVE) | | | | |
|--|---------|------------|----|--|
| Course Code | 18EE735 | CIE Marks | 40 | |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 | |
| Credits | 03 | Exam Hours | 03 | |
| Course Learning Objectives | | | | |

Course Learning Objectives:

- To identify the necessity of reactive power compensation.
- To describe load compensation.
- To select various types of reactive power compensation in transmission systems.
- To characterize distribution side and utility side reactive power management.
- To contrast reactive power coordination system.

Module-1

Theory of Load Compensation: Requirement for compensation, Objectives in load compensation, Ideal compensator, Acceptance standards for quality of supply, Specifications of aload compensator, Power factor correction and voltage regulations in single phase system: Power Factor and its Correction, Voltage regulation. T1. Classical load balancing problem: open loop balancing. R1.

Module-2

Theory of Steady State Reactive Power in Uncompensated & Compensated Transmission Line : Fundamental requirement in AC power transmission, advantages& disadvantages of different types of compensating equipment for transmission systems, fundamental transmission line equation, surge impedance and natural loading, voltage and current profiles of uncompensated line on open circuit, uncompensated line under load, effect of line length, load power and power factor on voltage and reactive power.

Compensated Transmission Line: Types of compensation, passive and active compensators, Uniformly distributed fixed compensation: Effect of distributed compensation on voltage control and effect of distributed compensation on line charging reactive power. T1

Module-3

Basics of Capacitors, Reactive Power of Capacitors, Arrangements and Reactive Power of Capacitors, Capacitors Connected in Parallel: Capacitors Connected in Series, Star and Delta Connection of Power Capacitors, Design of MV Capacitors . T2

Passive shunt compensation: Control of open circuit voltage with shunt reactors, required reactance values of shunt reactors. T1

Series compensation: Objectives and practical limitations, Symmetrical line with mid-point series capacitor and shunt reactor, Power transfer characteristics and maximum transmissible power Fundamental concepts of compensation by sectioning. T1

Module-4

Static Compensation: Practical applications of static compensators in electrical power systems, main types of compensators, principle of operation of Thyristor Controlled Reactor (TCR), Thyristor Controlled Transformer, TCR with shunt capacitors and Thyristor Switched Capacitor (TSC), principle of operation of saturated reactor compensators.

Series Capacitors: compensation factor, protective gear, Varistor protective gear, Resonance effects with series capacitors

Synchronous Condenser: Condenser operation, Power system Voltage control, Emergency reactivepower supply, HVDC application.

Comparison of basic types of compensator. T1

Module-5

Harmonics: Effect of harmonics on electrical equipment, resonance, shunt capacitors and filters, telephone interferences.

Reactive Power Co-ordination: Reactive power management, transmission benefits, reactive power dispatch & equipment impact.T1

Reactive Power Planning: Economic justification for reactive power planning, methods followed by the electricity boards in India, zonal reactive power requirements EHV & MV, low tension capacitors, placement in distribution, line capacitors. T3

- Distinguish the importance of load compensation in symmetrical as well as unsymmetrical loads.
- Observe various compensation methods in transmission lines.
- Distinguish demand side reactive power management & user side reactive power management.
- Construct model for reactive power coordination and effects of harmonics on electrical equipment.
- Discuss the Reactive Power Planning for the electricity boards.

| INDUSTRIAL DRIVE | SEMESTER – VII S AND APPLICATION (PR | OFESSIONAL ELECTIVE | E) |
|--|--|--|--|
| Course Code | 18EE741 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | 0 1 1 . | |
| • To define electric drive, its parts, adv | | of electric drive. | |
| • To explain dynamics and modes of o | • | | |
| • To explain selection of motor power | - | - | |
| • To analyze the performance of induct | | | |
| • To explain the control of induction m | | l stepper motor drives. | |
| To discuss typical applications electr | ical drives in the industry. | | |
| Module-1 | | | |
| Electrical Drives: Electrical Drives, | | rives. Parts of Electrical l | Drives, Choice o |
| Electrical Drives, Status of DC and ac | | | |
| Dynamics of Electrical Drives: Funda | | | |
| Operation. Equivalent Values of Drive | | | |
| Load Torques, Calculation of Time a | nd Energy Loss in Transie | nt Operations, Steady Sta | te Stability, Loa |
| Equalization. | Operation Speed Control on | d Drive Classifications Cl | locad loon Contr |
| Control Electrical Drives: Modes of (of Drives. | Operation, Speed Control an | u Drive Classifications, Cl | losed loop Collin |
| | | | |
| Module-2 | | | |
| Direct Current Motor Drives: Control of DC Separately Excited Motor, Three Phase Fully Cor | otor, Single Phase Half Con ntrolled Rectifier Control of | trolled Rectifier Control DC Separately Excited M | of DC Separatel lotor, Three Phas |
| Direct Current Motor Drives: Contr Control of DC Separately Excited Motor, Three Phase Fully Cor Half Controlled Rectifier Control of DO Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr | otor, Single Phase Half Con ntrolled Rectifier Control of C Separately Excited Motor, lled Rectifier, Rectifier Cont | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S | of DC Separatel lotor, Three Phas of DC Separatel upply Harmonics |
| Direct Current Motor Drives: Control Control of DC Separately Excited Mot Excited Motor, Three Phase Fully Cor Half Controlled Rectifier Control of D Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr of Series Motor. | otor, Single Phase Half Con ntrolled Rectifier Control of C Separately Excited Motor, lled Rectifier, Rectifier Cont | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S | of DC Separatel lotor, Three Phas of DC Separatel upply Harmonics |
| Direct Current Motor Drives: Contr Control of DC Separately Excited Motor, Three Phase Fully Cor Half Controlled Rectifier Control of DC Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr of Series Motor. Module-3 Induction Motor Drives: Analysis Unbalanced Source Voltage and Singl Induction Motor Fed From Non-Sinusoi | otor, Single Phase Half Con htrolled Rectifier Control of C Separately Excited Motor, lled Rectifier, Rectifier Cont rent, Chopper Control of Sep and Performance of Three le Phasing, Operation with idal Voltage Supply, Starting | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S arately Excited DC Motor Phase Induction Motors Unbalanced Rotor Impeda , Braking, Transient Analy | of DC Separatel lotor, Three Phas of DC Separatel supply Harmonics c, Chopper Contro s, Operation with ances, Analysis of rsis. Speed Contro |
| Module-2 Direct Current Motor Drives: Contr Control of DC Separately Excited Motor Excited Motor, Three Phase Fully Corr Half Controlled Rectifier Control of DC Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr of Series Motor. Module-3 Induction Motor Drives: Analysis Unbalanced Source Voltage and Singl Induction Motor Fed From Non-Sinusof Techniques-Stator Voltage Control, Va Module-4 | otor, Single Phase Half Con ntrolled Rectifier Control of C Separately Excited Motor, lled Rectifier, Rectifier Cont rent, Chopper Control of Sep and Performance of Three le Phasing, Operation with idal Voltage Supply, Starting riable Voltage Frequency Co | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S arately Excited DC Motor Phase Induction Motors Unbalanced Rotor Impeda , Braking, Transient Analy ontrol from Voltage Source | of DC Separatel lotor, Three Phas of DC Separatel supply Harmonics , Chopper Contro s, Operation wit unces, Analysis of rsis. Speed Contro es. |
| Direct Current Motor Drives: Contr Control of DC Separately Excited Motor, Three Phase Fully Cor Half Controlled Rectifier Control of D Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr of Series Motor. Module-3 Induction Motor Drives: Analysis Unbalanced Source Voltage and Singl Induction Motor Fed From Non-Sinusoi Techniques-Stator Voltage Control, Va | otor, Single Phase Half Con ntrolled Rectifier Control of C Separately Excited Motor, Iled Rectifier, Rectifier Cont rent, Chopper Control of Sep and Performance of Three le Phasing, Operation with idal Voltage Supply, Starting riable Voltage Frequency Co I):Voltage Source Inverter rter Rating for VSI and Cycl purce, Current Source (CSI e phase induction motors. ion from fixed frequency s | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S arately Excited DC Motor Phase Induction Motors Unbalanced Rotor Impeda , Braking, Transient Analy ontrol from Voltage Source (VSI) Control, Cycloco converter Induction Motor O Control, current regulate upply-starting, synchronom | of DC Separatel lotor, Three Phas of DC Separatel supply Harmonics of Comper Contro s, Chopper Contro s, Operation with ances, Analysis of vsis. Speed Contro es. |
| Direct Current Motor Drives: Contr Control of DC Separately Excited Motor, Excited Motor, Three Phase Fully Corr Half Controlled Rectifier Control of DC Excited Motor Fed Form Fully Control Power Factor and Ripple in Motor Curr of Series Motor. Module-3 Induction Motor Drives: Analysis Unbalanced Source Voltage and Singl Induction Motor Fed From Non-Sinusoi Techniques-Stator Voltage Control, Va Module-4 Induction Motor Drives (continued Closed Loop Speed Control and Conver Frequency Control from a Current So inverter control, speed control of single Synchronous Motor Drives: Operati | otor, Single Phase Half Con ntrolled Rectifier Control of C Separately Excited Motor, Iled Rectifier, Rectifier Cont rent, Chopper Control of Sep and Performance of Three le Phasing, Operation with idal Voltage Supply, Starting riable Voltage Frequency Co I):Voltage Source Inverter rter Rating for VSI and Cycl purce, Current Source (CSI e phase induction motors. ion from fixed frequency s | trolled Rectifier Control DC Separately Excited M Multi-quadrant Operation rol of DC Series Motor, S arately Excited DC Motor Phase Induction Motors Unbalanced Rotor Impeda , Braking, Transient Analy ontrol from Voltage Source (VSI) Control, Cycloco converter Induction Motor O Control, current regulate upply-starting, synchronom | of DC Separatel lotor, Three Phas of DC Separatel supply Harmonics of Comper Contro s, Chopper Contro s, Operation with ances, Analysis of vsis. Speed Contro es. |

- Explain the advantages, choice and control of electric drive
- Explain the dynamics, generating and motoring modes of operation of electric drives
- Explain the selection of motor power rating to suit industry requirements
- Analyze the performance & control of DC motor drives using controlled rectifiers
 Analyze the performance & control of converter fed Induction motor, synchronous motor & stepper motor drives.

| CHOICE BASED CREDIT SY | | | N (OBE) |
|--|---|---|--|
| μτι ιζατιόν ος ε | SEMESTER – VII LECTRICAL POWER (PRO | FESSIONAL ELECTIVE | |
| Course Code | 18EE742 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: To discuss electric heating, air-condit To explain laws of electrolysis, extract To explain the terminology of illumiting lamps. To explain design of interior and end | ction and refining of metals a nation, laws of illumination, exterior lighting systems- il | construction and working | - |
| ight fittings- factory lighting- flood lig To discuss systems of electric traction To discuss motors used for electric tr To discuss braking of electric mot Give awareness of technology of elec | n, speed time curves and med action and their control. ors, traction systems and p | oower supply and other t | |
| Module-1 Heating and welding: Electric Heating | | | |
| Extraction of Metals, Refining of Metal Module-2 Illumination: Introduction, Radiant H Measurement of Mean Spherical Ca Radiation and luminous Efficiency, for Different Purposes, Requirements o | Energy, Definitions, Laws on ndle Power by Integrating electric Lamps, Cold Cat | Sphere, Illumination Ph | otometer, Energy |
| Module-3 | r Good Eighting. | | |
| Electric Traction Speed - Time C of Traction, Systems of electric ' of Train Movement, Train Resistance Motors for Electric traction: Introduc (Series Type) are used to drive a Moto Induction Motor. Control of motors: Control of DC Multiple Unit Control, Control of Single | Traction, Speed - Time e, Adhesive Weight, Coeff tion, Series and Shunt Motor r Car, Tractive Effort and H Motors, Tapped Field C | Curves for Train Move icient of Adhesion. Its for Traction Services, Tw forse Power, AC Series M ontrol or Control by F | ement, Mechanics vo Similar Motors otor, Three Phase |
| Module-4 | | | |
| Braking: Introduction, Regenerative E Phase Series Motors, Mechanical brakin Brakes. Electric Traction Systems and P e | ng, Magnetic Track Brake, E ower Supply: System of | Electro – Mechanical Drum Electric Traction, AC | E Electrification |
| Transmission Lines to Sub - Stations, S and Distribution System for DC Tramy of Current Collection, Trolley Wires. | ways, Electrolysis by Curren | ÷ | e Booster, System |

Trams, Trolley Buses and Diesel – Electric Traction: Tramways, The Trolley – Bus, Diesel Electric Traction. **Module-5**

Electric Vehicles: Configurations of Electric Vehicles, Performance of Electric Vehicles, Tractive Effort in Normal Driving, Energy Consumption.

Hybrid Electric Vehicles: Concept of Hybrid Electric Drive Trains, Architectures of Hybrid Electric Drive Trains.

- Discuss different methods of electric heating & welding.
- Discuss the laws of electrolysis, extraction, refining of metals and electro deposition process.
- Discuss the laws of illumination, different types of lamps, lighting schemes and design of lighting systems.
- Analyze systems of electric traction, speed time curves and mechanics of train movement.Explain the motors used for electric traction, their control & braking and power supply system used for electric traction.

| B. E. ELECT CHOICE BASED CREDIT SY | RICAL AND ELECTRONICS YSTEM (CBCS) AND OUTCO SEMESTER – VII | | N (OBE) |
|--|--|--|--|
| AI TECHNIQUES FOR ELECTRIC AN | | HICLES (PROFESSIONA | L ELECTIVE) |
| Course Code | 18EE743 | CIE Marks | 40 |
| Teaching Hours/Week (L: T: P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: To explain IoT Based Battery M Vehicles (HEV) To explain advantages of AI, the u | se of brushless DC motor and | d its control in electric vel | nicle. |
| To explain the optimization technic electric vehicle. To explain the modelling and ana vehicles. | | c c | • |
| Module-1 IoT-Based Battery Management Sy System (BMS) for Hybrid Electric Veh HEV and Electric Vehicles (EV), Fund | nicles (HEV) : Introduction, I | Battery configuration, Ty | pes of batteries for |
| Module-2 | | | |
| Brushless Direct Current Motor Driv Vehicle: Basics of Artificial Intelligen Mathematical Representation Brushless Fuzzy Control, Auto-Tuning Type Fuz Controller, BLDC Motor Speed Cont Controllers. | nce, Advantages of Artificial s DC Motor, Closed-Loop Mo zy PID Controller, Genetic A | l Intelligence in EV, Bru odel of BLDC Motor Driv Algorithm, Artificial Neur | shless DC Motor, we, PID Controller, ral Network-Based |
| Module-3 Optimization Techniques Used in A Components of an Active Magnetic E Control Strategies for AMB in EVs. Module-4 | | | |
| Small-Signal Modeling Analysis of Overall System Modeling, Mathematic | | | ns: Introduction, |
| Module-5Energy Management ofHybrid EnIntroduction, Problem Description, and | | | us Driving Mode: |
| Course Outcomes: At the end of the complexity of the complexity of the end of the complexity of the end of the complexity of the end o | gement System and type of b or optimum operation of EV. g system for EVs. onverters for EV applications | atteries for EV and HEV. | |

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) **SEMESTER – VII** SMART GRID (PROFESSIONAL ELECTIVE) Course Code 18EE744 **CIE Marks** 40 Teaching Hours/Week (L: T: P) (3:0:0)SEE Marks 60 Credits 03 03 Exam Hours **Course Learning Objectives:** • To understand the basic concept of smart grid, attributes of Smart Grid • To describe the over view of the perfect power system configuration • To know about DC power delivering systems ,data centres and information technology loads • To educate the importance of Technology Alternatives in smart Grid • To understand the Dynamic energy systems in Smart Grid • To describe the overview of Demand side planning and evaluation. Module-1 Introduction: Introduction to smart grid, electricity network, local energy networks, electric transportation, low carbon central generation, attributes of the smart grid. Smart Grid to Evolve a Perfect Power System: Introduction, overview of the perfect power system configurations, device level power system, building integrated power systems, distributed power systems, fully integrated power system. Module-2 DC Distribution and Smart Grid: AC Vs. DC sources, benefits of and drives of DC power delivery systems, powering equipment and appliances with DC, data centers and information technology loads, potential future work and research Intelligrid Architecture for the Smart Grid: Introduction, launching intelligrid, intelligrid today, smart grid vision based on the intelligrid architecture. Module-3 Dynamic Energy Systems Concept: Smart energy efficient end use devices, smart distributed energy resources, advanced whole building control systems, integrated communications architecture, energy management, role of technology in demand response, current limitations to dynamic energy management, distributed energy resources, overview of a dynamic energy management, key characteristics of smart devices, key characteristics of advanced whole building control systems, key characteristics of dynamic energy management system. Module-4 Efficient Electric End Use Technology Alternatives: Existing technologies ,lighting, space conditioning, indoor air quality, domestic water heating, hyper efficient appliances, ductless residential heat pumps and air conditioners, variable refrigerant flow air conditioning, heat pump water heating, hyper efficient residential appliances, data center energy efficiency, LED street and area lighting, industrial motors and drives, equipment retrofit and replacement, process heating, cogeneration, thermal energy storage, industrial energy management programs, manufacturing process, electro -technologies, residential, commercial and industrial

sectors. Module-5

Demand side planning: Introduction, Selecting Alternatives, Issues Critical to the Demand-side Issues Critical to the Demand-side, The Utility Planning Process, Demand-side Activities, Alternatives that Are Most Beneficial.

Demand-Side Evaluation: Levels of Analysis. General Information Requirements, Context, Transferability, Data Requirement, Cost/Benefit Analysis, Program Interaction.

- Explain the concept of Smart grid enables the ElectricNet and need of smart grid.
- Outline the benefits and drivers of DC Power delivery system.
- Summarize the Intelligrid Architecture for the smart grid.
- Explain the Efficient Electric End-use Technology Alternatives.
- Discuss Demand side planning and Evaluation.

28

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER – VII

ARTIFICIAL NEURAL NETWORK WITH APPLICATIONS TO POWER SYSTEMS (PROFESSIONAL ELECTIVE)

| | (1101 200101 (122 2011 (2)) | | |
|-----------------------------|-----------------------------|------------|----|
| Course Code | 18EE745 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course Learning Objectives:

• To understand the fundamental concepts and models of Artificial Neural Systems.

• To understand neural processing, learning and adaptation, Neural Network learning rules.

• Ability to analyze multilayer feed forward networks.

• Ability to develop various ancillary techniques applied to power system and control of power systems.

Module-1

Fundamental Concepts and Models of Artificial Neural Systems

Biological Neurons and their artificial models – Biological Neuron, McCulloch-Pitts Neuron Model, Neuron modeling for Artificial neural systems. Models for Artificial Neural Networks – Feed forward Network, Feedback network.

Module-2

Neural Processing, Learning and Adaptation, Neural Network Learning Rules

Neural Processing. Learning and Adaptation – Learning as Approximation or Equilibria Encoding, Supervised and Unsupervised Learning. Neural Network Learning Rules – Hebbian Learning Rule, Perceptron Learning Rule, Delta Learning Rule, Widrow-Hoff Learning Rule, Correlation Learning Rule, Winner-Take-All Learning Rule, Outstar Learning Rule, Summary of Learning Rules.

Module-3

Multilayer Feedforward Networks

Feedforward Recall and Error Back-Propagation Training – Feedforward Recall, Error Back-Propagation Training, Training Errors and Multilayer Feedforward Networks as Universal Approximators (Excluding Examples). Learning Factors – Initial Weights, Cumulative Weight Adjustment versus Incremental Updating, Steepness of the Activation Function, Learning Constant, Momentum Method, Network Architectures Versus Data Representation, Necessary Number of Hidden Neurons.

Module-4

Neural Network and its Ancillary Techniques as Applied to Power Systems

Introduction, Learning versus Memorization, Determining the Best Net Size, Network Saturation, Feature Extraction, Inversion of Neural Networks, Alternative Training Method: Genetic Based Neural Network, Fuzzified Neural Network.

Module-5

Control of Power Systems

Introduction, Background, Neural Network Architectures for modeling and control, Supervised Neural Network Structures, Diagonal Recurrent Neural Network based Control System, Convergence and Stability.

- Develop Neural Network and apply elementary information processing tasks that neural network can solve.
- Develop Neural Network and apply powerful, useful learning techniques.
- Develop and Analyze multilayer feed forward network for mapping provided through the first network layer and error back propagation algorithm.
- Analyze and apply algorithmic type problems to tackle problems for which algorithms are not available.
- Develop and Analyze supervised/unsupervised, learning modes of Neural Network for different applications.

| | ICAL AND ELECTRONICS ENGI TEM (CBCS) AND OUTCOME BA | |) BE) |
|--|--|-------------------------|------------------|
| | SEMESTER – VII | | (21) |
| | PTURE AND STORAGE (OPEN EI | | |
| Course Code | 18EE751 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | 3:0:0 | SEE Marks | 60 |
| Credits Module-1 | 03 | Exam Hours | 03 |
| Introduction: The carbon cycle, Mit | tigating growth of the atmospheric | arhon inventory. Th | a pr ogod |
| of technology innovation. | tigating growth of the atmospheric | carbon inventory, Th | e process |
| Overview of carbon capture and st | orage: Carbon capture Carbon st | orage | |
| Power generation fundamentals: I | | | er nlant |
| Combined cycle power generation, F | • | | er plant, |
| Module-2 | uture developments in power-gene | ration technology. | |
| Carbon capture from power gen | neration: Introduction. Precombi | ustion capture. Postco | ombustio |
| capture, Oxyfuel combustion captur | | | |
| power plant, Approaches to zero-emi | | ,, | |
| Carbon capture from industrial | | Steel production, Oil | refining |
| Natural gas processing. | | I A | L L |
| Absorption capture systems: Chen | nical and physical fundamentals, | Absorption application | ns in post |
| combustion capture, Absorption tech | | | • |
| Module-3 | | | |
| Adsorption capture systems: Physi | ical and chemical fundamentals, A | Adsorption process ap | plications |
| Adsorption technology RD and D sta | itus. | | |
| Membrane separation systems: Ph | nysical and chemical fundamental | s, Membrane configur | ration an |
| preparation and module construction | | | |
| in pre-combustion capture, Membrar | | | |
| Membrane applications in postcom | bustion CO_2 separation, Membra | ane applications in n | atural ga |
| processing. | | | |
| Module-4 | | | |
| Cryogenic and distillation systems | | | |
| operation, Cryogenic oxygen produc | | Holmes process for | $CO_2 - CH$ |
| separation, RDand D in cryogenic an | e | tota of tashnalagy day | alamman |
| Mineral carbonation: Physical and | | tate of technology dev | elopmen |
| Demonstration and deployment outlo | | mantala Enhanced ail | |
| Geological storage: Introduction, C | | nentais, Ennanced on | recovery |
| Saline aquifer storage, Other geologic Module-5 | cal storage options. | | |
| Ocean storage: Introduction, Physic | cal chemical and biological fund | Jamentals Direct CO. | injection |
| Chemical sequestration, Biological se | 0 | $\frac{1}{2}$ | injectioi |
| Storage in terrestrial ecosystems: | * | emical fundamentals ' | Terrestrig |
| carbon storage options, Full GHG a | | | |
| storage. | counting for terrestriar storage, c | current ReeD Toeus III | torrestric |
| Other sequestration and use option | s: Enhanced industrial usage Alg | al biofuel production | |
| Carbon dioxide transportation: Pi | | | |
| L . | | 1 | |
| Course outcomes: | | | |
| At the end of the course the student v | | | |
| * | hange and the measures that can be | e taken to reduce emiss | ions. |
| • Discuss carbon capture and carbo | | | |
| • Explain the fundamentals of pow | • | | |
| - - | re from nower generation and indu | strial processes | |
| • Explain methods of carbon captu | | | |
| | methods: storage in coal seams, de | | and saline |

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER – VII

| ELECTRIC VEHICLES (OPEN ELECTIVE) | | | |
|-----------------------------------|---------|------------|----|
| Course Code | 18EE752 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |

Course objectives:

• To Understand the fundamental laws and vehicle mechanics.

• To Understand working of Electric Vehicles and recent trends.

• Ability to analyze different power converter topology used for electric vehicle application.

• Ability to develop the electric propulsion unit and its control for application of electric vehicles.

Module-1

Vehicle Mechanics: Roadway Fundamentals, Laws of Motion, Vehicle Kinetics, Dynamics of Vehicle Motion, Propulsion Power, Force-Velocity Characteristics, Maximum Gradability, Velocity and Acceleration, Constant FTR, Level Road, Velocity Profile, Distance Traversed, Tractive Power, Energy Required, Nonconstant FTR, General Acceleration, Propulsion System Design.

Module-2

Electric and Hybrid Electric Vehicles: Configuration of Electric Vehicles, Performance of Electric Vehicles, Traction motor characteristics, Tractive effort and Transmission requirement, Vehicle performance, Tractive effort in normal driving, Energy consumption Concept of Hybrid Electric Drive Trains, Architecture of Hybrid Electric Drive Trains, Series Hybrid Electric Drive Trains, Parallel hybrid electric drive trains.

Module-3

Energy storage for EV and HEV: Energy storage requirements, Battery parameters, Types of Batteries, Modelling of Battery, Fuel Cell basic principle and operation, Types of Fuel Cells, PEMFC and its operation, Modelling of PEMFC, Supercapacitors.

Module-4

Electric Propulsion:

EV consideration, DC motor drives and speed control, Induction motor drives, Permanent Magnet Motor Drives, Switch Reluctance Motor Drive for Electric Vehicles, Configuration and control of Drives.

Module-5

Design of Electric and Hybrid Electric Vehicles: Series Hybrid Electric Drive Train Design: Operating patterns, control strategies, Sizing of major components, power rating of traction motor, power rating of engine/generator, design of PPS Parallel Hybrid Electric Drive Train Design: Control strategies of parallel hybrid drive train, design of engine power capacity, design of electric motor drive capacity, transmission design, energy storage design.

Course outcomes:

At the end of the course the student will be able to:

- Explain the roadway fundamentals, laws of motion, vehicle mechanics and propulsion system design.
- Explain the working of electric vehicles and hybrid electric vehicles in recent trends.
- Model batteries, Fuel cells, PEMFC and super capacitors.
- Analyze DC and AC drive topologies used for electric vehicle application.
- Develop the electric propulsion unit and its control for application of electric vehicles.

| | SEMESTER – VII | OME BASED EDUCATION | N (UDE) |
|---|---|--|---|
| DISASTI | ERS MANAGEMENT (OPE | N FI FCTIVE) | |
| Course Code | 18EE753 | CIE Marks | 40 |
| Ceaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| To explain disaster management, To explain the role of IMD, cyclor To explain the role of different ins To explain the role of Central Wat draught management plan To explain reasons for the occurre | ne prediction and cyclone w stitutions, defence and other ter Commission in river wate | arning system in India services in natural disaster er sharing, Draught, its asse | management. |
| I o explain reasons for the occurre Iodule-1 | nee of earth quarte, Tourian | is and manderstorms. | |
| Disaster Management Plan (DMP): - Cyclones and their Hazard Potential: Over Indian Seas, Movement of Cyclqr Module-2 | Classification of Low-Pres | • | Cyclonic Storms |
| India Meteorological Department ar Cyclone Prediction and Dissemination hrough INSAT, Port Warnings with I Cyclones Disaster Management – Pla Early Warning. | of Warnings, Dissemination Day and Night hoisting Sib'T | on of Cyclone Warnings, G lals. | Cydone Warning |
| Module-3 | | | |
| n Disaster Management, Role of NG Disaster Management. | Os, Self Help Groups in D | isaster Management, Role | of Red Cross in |
| The Role of Defence and other Servic Role of Medical and Health Departme NDRF), Role of Remote Sensing in D | ent in Cyclone disaster man | t: Role of Air Force in Disa agement, National Disaste | ster Management r Response Forc |
| The Role of Defence and other Servic Role of Medical and Health Departme (NDRF), Role of Remote Sensing in D management. | ent in Cyclone disaster man | t: Role of Air Force in Disa agement, National Disaste | ster Management r Response Forc |
| The Role of Defence and other Service Role of Medical and Health Departme (NDRF), Role of Remote Sensing in D management. Module-4 4Floods: Water Wealth of India, Defin Warning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, D Microfinance in drought mitigation, Dre | nition of Flood, Role of Ce cions, Water Purification Tec prought Assessment, Drough | erral Water Commission, chnologies in Flood Affecte ught Management Plan, D at Parameters, Role of Ba | ster Management r Response Force Media in disaster Monsoons, Flood ed Areas. Drought Years fo nking, Insurance |
| The Role of Defence and other Service Role of Medical and Health Departme (NDRF), Role of Remote Sensing in D management. Module-4 4Floods: Water Wealth of India, Defin Warning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, D Microfinance in drought mitigation, Dro Module-5 | ent in Cyclone disaster man Disaster Management, Role of nition of Flood, Role of Ce tions, Water Purification Tec reaks in the Monsoon, Drou Drought Assessment, Drough ought Monitoring, Drought | entral Water Commission, chnologies in Flood Affecte ught Management Plan, D nt Parameters, Role of Ba Research Unit (IMD), Rain | ster Management r Response Forc Media in disaste Monsoons, Floo ed Areas. Drought Years fo nking, Insurance water harvesting |
| The Role of Defence and other Service Role of Medical and Health Departme NDRF), Role of Remote Sensing in D nanagement. Module-4 Floods: Water Wealth of India, Defin Warning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, D Microfinance in drought mitigation, Drought | ent in Cyclone disaster man Disaster Management, Role of nition of Flood, Role of Ce- tions, Water Purification Teo reaks in the Monsoon, Drou Drought Assessment, Drough ought Monitoring, Drought I ne Earth, Plate Techtonics, S lides and Avalanches, Volca Clouds: Climatology of Wo vnings of Thunderstorms, I | t: Role of Air Force in Disa agement, National Disaste of Broadcast, Educational entral Water Commission, chnologies in Flood Affecte ught Management Plan, D at Parameters, Role of Ba Research Unit (IMD), Rain Seismcity of India, Earthqu noes. orld Thunderstorms, Lightn Hailstorms, Tornadoes, W | ster Management r Response Forc Media in disaste Monsoons, Floo ed Areas. Drought Years fo nking, Insurance water harvesting take Forecast and ing, Some Effect Vaterspouts, Dust |
| The Role of Defence and other Service Role of Medical and Health Departme NDRF), Role of Remote Sensing in D management. Module-4 Floods: Water Wealth of India, Defin Varning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, D Microfinance in drought mitigation, Dro Module-5 Earth quakes: Interior Structure of the disaster management, Tsunamis, Lands Hazards associated with Convective of f Electric Shock, Favours and Frow Devils, Nowcasting, Summer Thunders Heat Waves in India. | ent in Cyclone disaster man Disaster Management, Role of nition of Flood, Role of Ce- cions, Water Purification Teo reaks in the Monsoon, Drou Drought Assessment, Drough ought Monitoring, Drought I ne Earth, Plate Techtonics, S lides and Avalanches, Volca Clouds: Climatology of Wo vnings of Thunderstorms, I storms over India, Cold Wa | t: Role of Air Force in Disa agement, National Disaste of Broadcast, Educational entral Water Commission, chnologies in Flood Affecte ught Management Plan, D at Parameters, Role of Ba Research Unit (IMD), Rain Seismcity of India, Earthqu moes. orld Thunderstorms, Lightn Hailstorms, Tornadoes, W ves and Heat Waves - Col | ster Management r Response Forc Media in disaste Monsoons, Floo ed Areas. Drought Years fo nking, Insurance water harvesting take Forecast and ing, Some Effect Vaterspouts, Dust |
| The Role of Defence and other Service Role of Medical and Health Department NDRF), Role of Remote Sensing in Department NDRF), Role of Remote Sensing in Department Module-4 Floods: Water Wealth of India, Definition Varning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, Definition Microfinance in drought mitigation, Drought Microfinance in drought mitigation, Drought Maximum Action Structure of the disaster management, Tsunamis, Lands Hazards associated with Convective of f Electric Shock, Favours and Frow Devils, Nowcasting, Summer Thunders Heat Waves in India. Course Outcomes: At the end of the comparison of the co | ent in Cyclone disaster man Disaster Management, Role of nition of Flood, Role of Ce- cions, Water Purification Teo reaks in the Monsoon, Drou Drought Assessment, Drough ought Monitoring, Drought I ne Earth, Plate Techtonics, S lides and Avalanches, Volca Clouds: Climatology of Wo vings of Thunderstorms, I storms over India, Cold Wa | et: Role of Air Force in Disa agement, National Disaste of Broadcast, Educational entral Water Commission, chnologies in Flood Affecte ught Management Plan, D at Parameters, Role of Ba Research Unit (IMD), Rain Seismcity of India, Earthqu noes. orld Thunderstorms, Lightn Hailstorms, Tornadoes, W ves and Heat Waves - Col | ster Management r Response Forc Media in disaste Monsoons, Floo ed Areas. Drought Years fo nking, Insurance water harvesting take Forecast and ing, Some Effect Vaterspouts, Dust |
| The Role of Defence and other Service Role of Medical and Health Departme NDRF), Role of Remote Sensing in D nanagement. Module-4 Floods: Water Wealth of India, Defin Varning Signals and Precautionary Act Drought: Meteorological Drought, Br Different Met Subdivision of India, D dicrofinance in drought mitigation, Dro Module-5 Earth quakes: Interior Structure of the lisaster management, Tsunamis, Lands Hazards associated with Convective of f Electric Shock, Favours and Frow Devils, Nowcasting, Summer Thunders | ent in Cyclone disaster man Disaster Management, Role of nition of Flood, Role of Ce- tions, Water Purification Teo reaks in the Monsoon, Drou Drought Assessment, Drough ought Monitoring, Drought I ne Earth, Plate Techtonics, S lides and Avalanches, Volca Clouds: Climatology of Wo vnings of Thunderstorms, I storms over India, Cold Wa | t: Role of Air Force in Disa agement, National Disaste of Broadcast, Educational entral Water Commission, chnologies in Flood Affecte ught Management Plan, D at Parameters, Role of Ba Research Unit (IMD), Rain Seismcity of India, Earthqu noes. orld Thunderstorms, Lightn Hailstorms, Tornadoes, W ves and Heat Waves - Col e to: potential | ster Managemen r Response Forc Media in disaste Monsoons, Floo ed Areas. Drought Years fo nking, Insurance water harvesting take Forecast and ing, Some Effect Vaterspouts, Dust |

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) **SEMESTER – VII** ELECTRICAL ENERGY CONSERVATION AND AUDITING (OPEN ELECTIVE) Course Code 18EE754 CIE Marks 40 Teaching Hours/Week (L:T:P) (3:0:0) SEE Marks 60 03 Credits 03 Exam Hours **Course objectives:** • Understand the current energy scenario and importance of energy conservation. • Understand the methods of improving energy efficiency in different electrical systems. • Realize energy auditing. • Explain about various pillars of electricity market design. • To explain the scope of demand side management, its concept and implementation issues and strategies. Module-1 **Energy Scenario:** Commercial and Non-commercial energy, primary energy resources, commercial energy production, final energy consumption, energy needs of growing economy, long term energy scenario, energy pricing, energy sector reforms, energy and environment, energy security, energy conservation and its importance, restructuring of the energy supply sector, energy strategy for the future, air pollution, climate change. Energy Conservation Act-2001 and its features. Module-2 Energy Efficiency in Electrical Systems: Electricity billing, Electrical load management and maximum demand Control, Maximum demand controllers; Power factor improvement, Automatic power factor controllers, efficient operation of transformers, energy efficient motors, Soft starters, Variable speed drives; Performance evaluation of fans and pumps. Flow control strategies and energy conservation opportunities in fans and pumps, Electronic ballast, Energy efficient lighting and measures of energy efficiency in lighting system. Module-3 Energy auditing: Introduction, Elements of energy audits, different types of audit, energy use profiles, measurements in energy audits, presentation of energy audit results. Module-4 Electricity vis-à-vis Other Commodities: Distinguishing features of electricity as a commodity, Four pillars of market design: Imbalance, Scheduling and Dispatch, Congestion Management, Ancillary Services. Framework of Indian power sector and introduction to the availability based tariff (ABT). Module-5 Energy Audit Applied to Buildings: Energy – Saving Measures in New Buildings, Water Audit, Method of Audit, General Energy – Savings Tips Applicable to New as well as Existing Buildings. Demand side Management: Scope of DSM, Evolution of DSM concept, DSM planning and Implementation, Load management as a DSM strategy, Applications of Load Control, End use energy conservation, Tariff options for DSM. Course outcomes: At the end of the course the student will be able to: • Analyze about energy scenario nationwide and worldwide, also outline Energy Conservation Act and its features. • Discuss load management techniques and energy efficiency. • Understand the need of energy audit and energy audit methodology. • Understand various pillars of electricity market design. • Conduct energy audit of electrical systems and buildings. • Show an understanding of demand side management and energy conservation.

VIII SEMESTER DETAILED SYLLABUS

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING Choice Based Credit System (CBCS) and Outcome Based Education (OBE) SEMESTER – VIII

| Course Code | 18EE81 | CIE Marks | 40 |
|--|-----------------------|------------------------------------|-------------------------|
| Number of Lecture Hours/Week | 3:0:0 | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| • To describe various levels of | f controls in power s | ystems and the vulnerability | y of the system. |
| • To explain components, ar | chitecture and config | guration of SCADA. | |
| • To explain basic generator speed governors and mathe | | | |
| To explain automatic gene interconnected power system | | age and reactive power co | ontrol in an |
| • To explain reliability and co | ontingency analysis, | state estimation and related | issues. |
| Module-1 | | | |
| Introduction: Operating States of | | | |
| Reliable Operation, Preventive and | | | |
| Supervisory Control and Data | | | |
| Power System, basic functions and communication subsystem, IED fur | | | n, components of RTU |
| Classification of SCADA system: | 0 | e | nultiple RTU; Multipl |
| master-multiple RTUs; and Single r | naster, multiple subm | aster, multiple remote. 1 2 | |
| Module-2 | | | |
| Automatic Generation Control (A | GC): Introduction, S | Schematic diagram of load f | requency and excitation |
| voltage regulators of turbo generato | rs, Load frequency c | ontrol (Single area case), T | urbine speed governin |
| system, Model of speed governing sy | stem, Turbine mode | , Generator load model, Con | mplete block diagram o |
| nonnegantation of load fragmanary as | ntrol of an isolated | norman arratam. Staady, state | analysia Control and |

system, Model of speed governing system, Turbine model, Generator load model, Complete block diagram of representation of load frequency control of an isolated power system, Steady state analysis, Control area concept, Proportional plus Integral Controller. **T**1

Module-3

Automatic Generation Control in Interconnected Power system: Two area load frequency control, Optimal (Two area) load frequency control by state variable, Automatic voltage control, Load frequency control with generation rate constraints (GRCs), Speed governor dead band and its effect on AGC, Digital LF Controllers, Decentralized control. **1**

Module-4

Control of Voltage and Reactive Power: Introduction, Generation and absorption of reactive power, Relation between voltage, power and reactive power at a node, Methods of voltage control: i. Injection of reactive power, Shunt capacitors and reactors, Series capacitors, Synchronous compensators, Series injection. ii Tap changing transformers. Combined use of tap changing transformers and reactive power injection, Booster transformers, Phase shift transformers, Voltage collapse. \blacksquare 3

Module-5

Power System Security: Introduction, Factors affecting power system security, Contingency Analysis, Linear Sensitivity Factors, AC power flow methods, Contingency Selection and Ranking. T2

State estimation of Power Systems: Introduction, Linear Least Square Estimation. T2

- Describe various levels of controls in power systems, architecture and configuration of SCADA.
- Develop and analyze mathematical models of Automatic Load Frequency Control.
- Develop mathematical model of Automatic Generation Control in Interconnected Power system
- Discuss the Control of Voltage, Reactive Power and Voltage collapse.
- Explain security, contingency analysis, state estimation of power systems.

| | RICAL AND ELECTRONICS EN YSTEM (CBCS) AND OUTCOME | | ON (OBE) |
|--|---|--|---|
| | SEMESTER – VIII | | OIT (ODE) |
| | C TRANSMISSION (PROFESSIO | | 1 |
| Course Code | 18EE821 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: To discuss transmission interconnic capability, dynamic stability considerates parameters. To explain the basic concepts, definite chnology. To describe shunt controllers, Static power in the transmission system in the transmission system. To describe the basic components of by the converter. Explain converter control for HVDC system, What Limits the Limits the Limit system. | derations of a transmission nitions of flexible ac transmissio Var Compensator and Static Con- enhancing the controllability and istor-Controlled Series Capacitor I of the transmission line current. power transmission, overview and a converter, the methods for comp systems, commutation failure, con- tem Considerations: Transmiss loading Capability? Power Flow | AC System, lim interconnection n systems and ben mpensator for injend power transfer r (TCSC) and the nd organization of pensating the reaction atrol functions. | and controllable efits from FACTS ecting reactive capability. Static Synchronous HVDC system. ve power demanded |
| of a Transmission Interconnection, Re Controllers, Brief Description and De FACTS Technology, In Perspective: H Module-2 | efinitions of FACTS Controllers | | |
| Static Shunt Compensators: Object Segmentation, End of Line Voltage Stability. Methods of Controllable V Switched Reactor (TSR), Thyristor Switching Converter Type Var Generat Static VAR Compensators: SVC and and SVC, V –I and V –Q Character | Support to Prevent Voltage In Var Generation –Thyristor contr Switched Capacitor (TSC).Oper tors, Basic Operating Principles, E d STATCOM, the Regulation Slo | stability, Improve colled Reactor (Te cation of Single P Basic Control Appro ope. Comparison b | ment of Transient CR) and Thyristor hase TSC – TSR. paches. |
| Module-3 | | | |
| Static Series Compensators: Obje Compensation, Voltage Stability, In Capacitor, Thyristor-Switched Series C Series Compensator, Transmitted Pow | provement of Transient Stabili apacitor, Thyristor-Controlled Se | ty. GTO Thyristo ries Capacitor, The | r-Controlled Series |
| Module-4 | | | |
| Development of HVDC Technology: Overview and Organization of HVD Power Conversion: 3-Phase Converter | C Systems, HVDC Characteristi | ics and Economi | ic Aspects. |
| Module-5 | | | |
| Control of HVDC Converter and Sys HVDC Control and Design, HVDC | | | |
| Course Outcomes: At the end of the c Discuss transmission interconnection dynamic stability considerations of a tr Explain the basic concepts, definit technology. | ns, flow of Power in an AC Sy ansmission interconnection and co | ontrollable parameter | ers. |

• Describe shunt controllers, Static Var Compensator and Static Compensator for injecting reactive power in the transmission system in enhancing the controllability and power transfer capability.

• Describe series Controllers Thyristor-Controlled Series Capacitor (TCSC) and the Static Synchronous Series Compensator (SSSC) for control of the transmission line current.

• Explain advantages of HVDC power transmission, overview and organization of HVDC system.

• Describe the basic components of a converter, the methods for compensating the reactive power demanded by the converter.

• Explain converter control for HVDC systems, commutation failure, control.

| B. E. ELECT | RICAL AND ELECTRONIC | S ENGINEERING | |
|---|--|--|--|
| CHOICE BASED CREDIT SY | | OME BASED EDUCATION | N (OBE) |
| SEMESTER – VIII ELECTRICAL ESTIMATION AND COSTING (PROFESSIONAL ELECTIVE) | | | |
| Course Code | 18EE822 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| • To discuss the purpose of estimation a | and costing. | | |
| • To discuss market survey, estimated | s, purchase enquiries, tende | ers, comparative statemen | t and payment of |
| bills and Indian electricity act and some | e of the rules. | | |
| · To discuss distribution of energy in | a building, wiring and m | nethods of wiring, cables u | sed in internal |
| wiring, wiring accessories, fittings and | fuses. | | |
| • To discuss design of lighting points a | nd its number, total load, sul | b-circuits, size of conducto | r. |
| • To discuss different types of service r | | | |
| To discuss estimation of overhead tra | | | |
| • To discuss main components of a su | ibstation, their graphical r | epresentation and prepara | ation of single |
| line diagram of a substation. | | | |
| Module-1 | | | |
| Labour Conditions, Determination of Purchase System, Purchase Enquiry a Purchase Orders, Payment Of Bills, T and IE Rules -29,30,45,46,47,50,51,54, Module-2 | nd Selection of Appropriat ender Form, General Idea 55,77 and79. | te Purchase Mode, Compa a about IE Rule, Indian E | rative Statement, Electricity(IE) Act |
| Wiring: Introduction, Distribution of Desirabilities of Wiring. Types of cab and Specification of Cables. | | | |
| Wiring (continued): Main Switch a Lighting Accessories and Fittings, Ty Internal Wiring: General rules for wi Book), Number of Points, Determinati Distribution Board and Size of Conduct | pes of Fuses, Size of Fuse, ring, Design of Lighting Pe on of Total Load, Number | , Fuse Units, Earthing Co bints (Refer to Seventh Ch of Sub –Circuits, Ratings | onductor. hapter of the Text |
| Module-3 | | | |
| Service Mains: Introduction, Types, E and Estimation of Power Circuits: In Wiring, Input Power, Input Current to Board Main Switch and Starter. | ntroduction, Important Co | nsiderations Regarding M | Aotor Installation |
| Module-4 | acion and Distribution | | Lina Supports |

Estimation of Overhead Transmission and Distribution Lines: (Review of Line Supports, Conductor Materials, Size of Conductor for Overhead Transmission Line, Types of Insulators) [No Question Shall be Set From the Review Portion].

Cross Arms, Pole Brackets and Clamps, Guys and Stays, Conductors Configuration Spacing and Clearances, Span Lengths, Lightning Arrestors, Phase Plates, Danger Plates, Anti Climbing Devices, Bird Guards, Beads of Jumpers, Muffs, Points to be Considered at the Time of Erection of Overhead Lines, Erection of Supports, Setting of Stays, Fixing of Cross Arms, Fixing of Insulators, Conductor Erection. Repairing and Jointing of Conductors, Dead End Clamps, Positioning of Conductors and Attachment to Insulator s, Jumpers, Tee-Offs, Earthing of Transmission Lines, Guarding of Overhead Lines, Clearances of Conductor From Ground, Spacing Between Conductors, Important Specifications.

Module-5

Estimation of Substations: Main Electrical connection, Graphical Symbols for Various Types of Apparatus and Circuit Elements on Substation main Connection Diagram, Single Line Diagram of Typical Substations, Equipment for Substation, Substation Auxiliaries Supply, Substation Earthing.

Course Outcomes: At the end of the course the student will be able to:

• Discuss wiring methods, cables used, design of lighting points and sub-circuits, internal wiring, wiring accessories and fittings, fuses and types.

- Discuss estimation of service mains and power circuits.
- Discuss estimation of overhead transmission and distribution system its components.
- Discuss types of substation, main components and estimation of substation.

| | | OME BASED EDUCATION | N (OBE) |
|--|--|--|---|
| | SEMESTER – VIII | | |
| Course Code | CS IN POWER SYSTEMS (PI 18EE823 | CIE Marks | <u>40</u> |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course objectives: | 05 | Lixani Hours | 05 |
| • To define big data and to explain | n big data application and anal | vtice to power systems | |
| To explain the role of big data in systems. To explain security methods for detection in power systems. | n smart grid communications a | nd optimization of big data | • |
| • To explain the application of un | it commitment method in the c | control of smart grid. | |
| • To explain protection algorithm | for transformer based on data | pattern recognition. | |
| Module-1 | | | |
| Introduction: Big Data, Future Powe | er Systems | | |
| Big Data Application and Analytics Big Data, Algorithms for Processing Module-2 | | | a Applications o |
| Role of Big Data in Smart Grid | | | |
| Flow of Information in a Smart Scena of Study. Big Data Optimization in Electric I Data, Big Data and Power Systems, C | Power Systems: Introduction, | Background, Scientometri | - |
| Module-3 | | | |
| Security Methods for Critical I Communication System Threats, Ger Operations, High-Level Communicat for Electricity Theft Detection: Intr Methods, Data Mining and Electrici Research. | neral Communication System (ion System Threats, Cyber Th roduction, Transmission and D | Dperations, Industrial Cont reats and Security. Data - Distribution System Losses, | rol Networks and Mining Method , Electricity Thef |
| N/ 1 1 / | | | |
| Module-4 | | | |
| Unit Commitment Control of Sma | | | |
| Module-4 Unit Commitment Control of Sma Commitment Problem, A Multi-agent Module-5 | | | |
| Unit Commitment Control of Sma Commitment Problem, A Multi-agent Module-5 Transformer Differential Protection System Protection, Methods for Diffe Component Analysis (CCA), PCA Ag Transformers, Application of the CCA Course outcomes: | t Architecture, Illustrative Exa on Algorithm Based on Data erential Protection Blocking, P pplied to Discriminate Between A as a Base for a Differential F | mple. Pattern Recognition: Big rincipal Component Analys n Inrush and Fault, Current | The Unit Data and Power sis, Curvilinear s in |
| Unit Commitment Control of Sma Commitment Problem, A Multi-agent Module-5 Transformer Differential Protection System Protection, Methods for Differ Component Analysis (CCA), PCA Ag Transformers, Application of the CCA | t Architecture, Illustrative Exa on Algorithm Based on Data erential Protection Blocking, Prophied to Discriminate Between A as a Base for a Differential Protection Blocking, Prophied to Discriminate Between and the Between A as a Base for a Differential Protection Blocking, Prophied to Discriminate Between A as a Base for a Differential Protection Blocking, Prote | mple. Pattern Recognition: Big rincipal Component Analys n Inrush and Fault, Current Protection System Under St able to power systems and models in power systems. | The Unit Data and Power sis, Curvilinear s in udy, Results. in particular to |

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) **SEMESTER – VIII** POWER SYSTEM PLANNING (PROFESSIONAL ELECTIVE) Course Code 18EE824 CIE Marks 40 Teaching Hours/Week (L:T:P) (3:0:0)SEE Marks 60 Credits 03 Exam Hours 03 **Course Learning Objectives:** • To discuss primary components of power system planning namely load furcating, evaluation of energy resources, provisions of electricity Act and Energy Conservation Act. • To explain planning methodology for optimum power system expansion, various types of generation, transmission and distribution. • To explain forecasting of anticipated future load requirements of both demand and energy by deterministic and statistical techniques using forecasting tools. • To discuss methods to mobilize resources to meet the investment requirement for the power sector. • To perform economic appraisal to allocate the resources efficiently and take proper investment decisions • To discuss expansion of power generation and planning for system energy in the country • To discuss evaluation of operating states of transmission system, their associated contingencies and determination of the stability of the system for worst case conditions • To discuss principles of distribution planning, supply rules, network development and the system studies. • To discuss reliability criteria for generation, transmission, distribution and reliability evaluation and analysis. • To discuss grid reliability, voltage disturbances and their remedies. • To discuss planning and implementation of electric –utility activities designed to influence consumer uses of electricity. • To discuss market principles and the norms framed by CERC for online trading and exchange in the interstate power market. Module-1 Power System: Planning Principles, Planning Process, Project Planning, Power Development, National and Regional Planning, Enterprise Resources Planning, Planning Tools, Power Planning Organisation, Scenario Planning. Electricity Forecasting: Load Requirement, System Load, Electricity Forecasting, Forecasting Techniques, Forecasting Modelling, Spatial – Load Forecasting, Peak Load - Forecast, Reactive – Load Forecast, Unloading of a System. Module-2 **Power-System Economics:** Financial Planning, Techno – Economic Viability, Private Participation, Financial Analysis, Economic Analysis, Transmission, Rural Electrification Investment, Total System Analysis, Credit -Risk Assessment. Generation Expansion: Generation Capacity and Energy, Generation Mix, Clean Coal Technologies Renovation and Modernisation of Power Plants. Module-3 **Transmission Planning:** Transmission Planning Criteria, Right – of – Way, Network Studies, High – Voltage Transmission, HVDC Transmission, Conductors, Sub – Stations, Power Grid, Reactive Power Planning, Energy Storage. Module-4 Distribution: Distribution Deregulation, Planning Principles, Electricity – Supply Rules, Criteria and Standards, Sub – Transmission, Basic Network, Low Voltage Direct Current Electricity, Upgradation of Existing Lines and Sub – Stations, Network Development, System Studies, Urban Distribution, Rural Electrification. Reliability and Quality: Reliability Models, System Reliability, Reliability and Quality Planning, Functional Zones, Generation Reliability Planning Criteria, Transmission Reliability Criteria, Distribution Reliability, Reliability Evaluation, Grid Reliability, Quality of Supply.

Module-5

Demand-Side Planning: Demand Response, Demand – Response Programmes, Demand– Response Technologies, Energy Efficiency, Energy - Economical Products, Efficient – Energy Users, Supply – Side Efficiency, Energy Audit.

Electricity Market: Market Principles, Power Pool, Independent System Operator, Distribution SystemOperator, Power Markets, Market Rules, Bidding, Trading, Settlement System, Merchant Power, Differential Electricity, Congestion Management, Ancillary Services, Hedging, Smart Power Market.

Course Outcomes: At the end of the course the student will be able to:

• Discuss primary components of power system planning, planning methodology for optimum power system expansion and load forecasting.

• Understand economic appraisal to allocate the resources efficiently and appreciate the investment decisions

• Discuss expansion of power generation and planning for system energy in the country, evaluation of operating states of transmission system, their associated contingencies and the stability of the system.

• Discuss principles of distribution planning, supply rules, network development and the system studies

• Discuss reliability criteria for generation, transmission, distribution and reliability evaluation and analysis, grid reliability, voltage disturbances and their remedies

• Discuss planning and implementation of electric -utility activities, market principles and the norms framed.

B. E. ELECTRICAL AND ELECTRONICS ENGINEERING CHOICE BASED CREDIT SYSTEM (CBCS) AND OUTCOME BASED EDUCATION (OBE) SEMESTER – VIII

| ELECTRICAL POWER QUALITY (PROFESSIONAL ELECTIVE) | | | |
|---|-------------------------------------|---------------------|--------------|
| Course Code | 18EE825 | CIE Marks | 40 |
| Teaching Hours/Week (L:T:P) | (3:0:0) | SEE Marks | 60 |
| Credits | 03 | Exam Hours | 03 |
| Course Learning Objectives: | | | |
| • Review definitions and standards of a | common power quality phenomena. | | |
| • Understand power quality monitoring | g and classification techniques. | | |
| • Investigate different power quality pl | enomena causes and effects. | | |
| • Understand different techniques for p | ower quality problems mitigation. | | |
| • Understand the various power quality | | e e | ion methods. |
| • Understand the effects of various pov | ver quality phenomenon in various | equipment. | |
| Module-1 | | | |
| Introduction: Power quality-voltage quality, power quality evaluation procedures term and definitions: general classes of power quality problems, transients, long duration voltage variation, short duration voltage variations, voltage imbalance, waveform distortion, power quality terms. | | | |
| Module-2 | | | |
| Voltage sags and interruptions: Sources of sags and interruptions, estimating voltage sag performance, fundamental principles of protection, motor starting sags. Transient over voltages: Sources of transient over voltages, principles of over voltages protection, utility capacitor switching transients. | | | |
| Module-3 | | | |
| Transient over voltages: Fundamentals of harmonics: Harmonic distortion, voltage versus transients, | | | |
| harmonic indexes, harmonic sources from commercial loads, harmonic sources from Industrial loads, | | | |
| effects of harmonic distortion, intra harmonics. | | | |
| Module-4 | | | |
| Applied harmonics: Harmonic distor | tion evaluations, principles for co | ontrolling harmonic | s, harmonic |

Applied harmonics: Harmonic distortion evaluations, principles for controlling harmonics, harmon studies, devices for controlling harmonic distortion, harmonic filters, standards of harmonics. **Power Quality Benchmark:** Introduction, benchmark process, power quality contract.

Module-5

Power quality benchmark: power quality state estimation, including power quality in distribution planning. **Distributed generation and quality:** DG technologies, interface to utility system, power quality issues, interconnection standards.

- Define Power quality; evaluate power quality procedures and standards.
- Estimate voltage sag performance; explain principles of protection and Sources of transient over voltages.
- Identify various sources of harmonics, explain effects of harmonic distortion.
- Evaluate harmonic distortion, control harmonic distortion.
- Estimate power quality in distribution planning. Identify power quality issues in utility system.